# TENSOR PRODUCTS OF ABELIAN GROUPS 

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1. Introduction. Let $G$ and $H$ be Abelian groups. Their direct sum $G \oplus H$ consists of all pairs ( $g, h$ ), with $(g, h)+\left(g^{\prime}, h^{\prime}\right)=\left(g+g^{\prime}, h+h^{\prime}\right)$. If we consider $G$ and $H$ as subgroups of $G \oplus H$, with elements $g=(g, 0)$ and $h=(0, h)$, then we may form $g+h$, and the ordinary laws of addition hold. Our object in this paper is to construct a group $G \circ H$ from $G$ and $H$, in which we can form $g \cdot h$, with the properties of multiplication; that is, the distributive laws

$$
\begin{equation*}
\left(g+g^{\prime}\right) \cdot h=g \cdot h+g^{\prime} \cdot h, \quad g \cdot\left(h+h^{\prime}\right)=g \cdot h+g \cdot h^{\prime} \tag{1.1}
\end{equation*}
$$

hold. Clearly $G \circ H$ must contain elements of the form $\sum g_{i} \cdot h_{i}$; it turns out (Theorem 1) that with these elements, assuming only (1.1), we obtain an Abelian group, which we shall call the tensor product of $G$ and $H .{ }^{1}$

The tensor product is known in one important case; namely, in tensor analysis (see $\S 4$, (b), and $\S 11$ ), though the definition in the form here given does not seem to have been used. Certain other cases are known (see §4). We refer to the examples there given for further indications of the scope of the theory. A direct product of algebras has been constructed by J. L. Dorroh, ${ }^{2}$ by methods closely allied to those of the present paper.

As is to be expected, we see in Part I that when we multiply several groups together, the associative and commutative laws hold; also the distributive laws with respect to direct sums and difference groups. The group of integers plays the rôle of a unit group. ${ }^{3}$ The rest of Part I is devoted largely to a study of the relation between groups with operator rings and tensor products; in particular, divisibility properties are considered.

In Part II, a detailed study of tensor products of linear spaces is made; we now assume $r g \cdot h=g \cdot r h(r$ real). With any element $\alpha$ of $G \circ H$ are associated subspaces $G(\alpha)$ of $G$ and $H(\alpha)$ of $H$; their dimensions equal the minimum number of terms in an expression $\sum g_{i} \cdot h_{i}$ for $\alpha$, and in this expression the $g_{i}$ and $h_{i}$ form bases in $G(\alpha)$ and $H(\alpha)$. The elementary operations of tensor algebra are derived, and a direct manner of introducing covariant differentiation is indicated. ${ }^{4}$ If the linear spaces are topological, a topology may be introduced into

[^0]the tensor product. If the spaces are not of finite dimension, there are of course various topologies possible in the product; the one we give is probably at an extreme end, in that a neighborhood of 0 in any topology will contain a neighborhood of the sort here given. The topology has certain defects in that the associative and distributive laws seem not to hold in general with topology preserved. In the case of Hilbert spaces, there is a natural definition of the topology in the product (see Murray and von Neumann, reference in §4, (c)). In the intermediate case of Banach spaces, probably the norm $|\alpha|$ may be defined as the lower bound of numbers $\sum\left|g_{i}\right|\left|h_{i}\right|$ for expressions $\sum g_{i} \cdot h_{i}$ of $\alpha .^{5}$

In topological groups which contain denumerable dense sets, the product may be given a topology, as is shown in Part III; it agrees with that in Part II when both are defined. Again, in complicated groups, other topologies are possible and perhaps preferable. Finally, for a more complete theory, one must allow infinite sums $\sum g_{i} \cdot h_{i}$.
2. Notations. Write $G \approx H$ if $G$ and $H$ are isomorphic. The symbol 0 means the zero in any group, or the group with only the zero element. $A \cap B$ is the set of elements in both $A$ and $B . \quad a g$ ( $a$ an integer $>0$ ) means $g+\cdots+g$ ( $a$ terms); $(-a) g=a(-g), 0 g=0 . \quad g+A$ is the set of all $g+g^{\prime}, g^{\prime}$ in $A$; similarly for $A+B . \quad g \cdot B$ is the set of all $g \cdot h, h$ in $B$, etc. $\quad a A=$ all $a g, g$ in $A$. Note that $2 A \subset A+A$, etc. Write $a \mid g$ if there is a $g^{\prime}$ with $a g^{\prime}=g ; g$ is then "divisible" by the integer $a . \quad a \mid A$ means $a \mid g$ for all $g$ in $A . \quad G$ is "completely divisible" if for every $a \neq 0, a \mid G$, i.e., $a G=G$. The "nullifier" of $H$ in $G$ (of $G$ in $H$ ) is the set of all $g$ (all $h$ ) such that $g \cdot h=0$ for all $h$ in $H$ (all $g$ in $G$ ).

Let $\sum^{*} A$ denote the set of all finite sums $a_{1}+\cdots+a_{k}, a_{i}$ in $A$, any $k$; this is a subgroup of $G$ (if $A \subset G$ ). $\quad \sum_{i}^{*} A_{i}$ is the set of all $a_{1}+\cdots+a_{k}\left(a_{i}\right.$ in $A_{i}$, any $k$ ).

Let $G \oplus H$ and $G \ominus G^{\prime}$ denote direct sums and difference groups. There is a "natural homomorphism" of $G$ into $G \ominus G^{\prime}$. Some particular groups we shall use are: $I_{0}=$ group of integers; $I_{\mu}=I_{0} \Theta \mu I_{0}=$ integers $\bmod \mu$ (with elements $a_{\mu}$ for integral $a$ ); $R t=$ rational numbers $; R l=$ real numbers. Set $G_{\mu}=$ $G \in \mu G$.

## I. Discrete groups

3. Discrete tensor products. Let $G$ and $H$ be groups (not necessarily Abelian), with the operation + . Let $\mathfrak{S}$ be the set of all symbols

$$
\left(g_{1}, h_{1} ; \cdots ; g_{n}, h_{n}\right) \quad\left(g_{i} \text { in } G, h_{i} \text { in } H, n \text { any integer }>0\right)
$$

We add two symbols by the rule

$$
\left(g_{1}, h_{1} ; \cdots\right)+\left(g_{n+1}, h_{n+1} ; \cdots\right)=\left(g_{1}, h_{1} ; \cdots ; g_{n+1}, h_{n+1} ; \cdots\right)
$$

[^1]Clearly + is associative. We may put any element of $\mathbb{S}$ in the normal form $\left(g_{1}, h_{1}\right)+\cdots+\left(g_{n}, h_{n}\right)$; if we write

$$
g_{i} \times h_{i}=\left(g_{i}, h_{i}\right),
$$

we obtain

$$
\left(g_{1}, h_{1} ; \cdots ; g_{n}, h_{n}\right)=g_{1} \times h_{1}+\cdots+g_{n} \times h_{n}
$$

Define two equivalence relations as follows:

$$
\begin{align*}
& \cdots+\left(g+g^{\prime}\right) \times h+\cdots \sim \cdots+g \times h+g^{\prime} \times h+\cdots  \tag{3.1}\\
& \cdots+g \times\left(h+h^{\prime}\right)+\cdots \sim \cdots+g \times h+g \times h^{\prime}+\cdots \tag{3.2}
\end{align*}
$$

Any succession $s_{1} \sim s_{2} \sim \ldots \sim s_{p}$ we shall call an equivalence sequence between $s_{1}$ and $s_{p}$. If two elements $s, s^{\prime}$ are joined by an equivalence sequence, we say they are equivalent, $s \sim s^{\prime}$. Let also $s \sim s$. The elements of $\subseteq$ fall into subsets under this relation; these form the elements of the discrete tensor product $G \circ H$. In case $G$ and $H$ are discrete, we call this the tensor product, in agreement with the definition in Part III. Let $\sum g_{i} \cdot h_{i}=g_{1} \cdot h_{1}+\cdots$ be the element of $G \circ H$ containing the element $\sum g_{i} \times h_{i}$ of $\mathbb{S}$.

To define the group operation, which we temporarily call $\oplus$, in $G \circ H$, take any $\alpha$ and $\alpha^{\prime}$, and let $\sum g_{i} \times h_{i}$ and $\sum g_{i}^{\prime} \times h_{i}^{\prime}$ be corresponding elements of S; we set

$$
\begin{equation*}
\alpha \oplus \alpha^{\prime}=\sum g_{i} \cdot h_{i}+\sum g_{i}^{\prime} \cdot h_{i}^{\prime} \tag{3.3}
\end{equation*}
$$

We must show that this is independent of the choices of $s=\sum g_{i} \times h_{i}$ and $s^{\prime}=$ $\sum g_{i}^{\prime} \times h_{i}^{\prime}$. If we had chosen $t$ and $t^{\prime}$, then there are equivalence sequences joining $s$ to $t$ and $s^{\prime}$ to $t^{\prime}$; applying these sequences to $\sum g_{i} \times h_{i}+\sum g_{i}^{\prime} \times h_{i}^{\prime}$ shows that the same element $\alpha \oplus \alpha^{\prime}$ is determined. Henceforth we use + instead of $\oplus$. Note that + is associative, and (1.1) holds.

We prove in succession the following facts.
(a)

$$
\begin{array}{r}
g \cdot 0=(g+g-g) \cdot 0=g \cdot 0+g \cdot 0+(-g) \cdot 0=g \cdot(0+0)+(-g) \cdot 0 \\
=g \cdot 0+(-g) \cdot 0=(g-g) \cdot 0=0 \cdot 0
\end{array}
$$

similarly $0 . h=0.0$.
(b)

$$
g \cdot h+0 \cdot 0=g \cdot h+g \cdot 0=g \cdot(h+0)=g \cdot h,
$$

and hence $0 \cdot 0=g \cdot 0=0 \cdot h$ plays the rôle of the identity.
(c)

$$
\begin{aligned}
g \cdot h=g \cdot h+0 \cdot(-h)=g \cdot h+g \cdot(-h) & +(-g) \cdot(-h) \\
& =g \cdot 0+(-g) \cdot(-h)=(-g) \cdot(-h) .
\end{aligned}
$$

Next, we may operate with the product as if $G$ and $H$ were Abelian. For
(d)

$$
g \cdot\left(h+h^{\prime}\right)=g \cdot h+g \cdot h^{\prime}=(-g) \cdot(-h)+(-g) \cdot\left(-h^{\prime}\right)
$$

$$
=(-g) \cdot\left(-h-h^{\prime}\right)=g \cdot\left(h^{\prime}+h\right) ;
$$

similarly $\left(g+g^{\prime}\right) \cdot h=\left(g^{\prime}+g\right) \cdot h$. Also

$$
\begin{aligned}
g \cdot\left(h+h^{\prime}+h^{\prime \prime}\right)=g \cdot h+g \cdot\left(h^{\prime}+h^{\prime \prime}\right)=g \cdot h+g \cdot\left(h^{\prime \prime}\right. & \left.+h^{\prime}\right) \\
& =g \cdot\left(h+h^{\prime \prime}+h^{\prime}\right), \text { etc. }
\end{aligned}
$$

Finally, the operation in $G \circ H$ is commutative. For ${ }^{6}$
$\alpha=\left(g+g^{\prime}\right) \cdot\left(h^{\prime}+h\right)=g \cdot\left(h^{\prime}+h\right)+g^{\prime} \cdot\left(h^{\prime}+h\right)$

$$
=g \cdot h^{\prime}+g \cdot h+g^{\prime} \cdot h^{\prime}+g^{\prime} \cdot h
$$

also

$$
\alpha=\left(g+g^{\prime}\right) \cdot h^{\prime}+\left(g+g^{\prime}\right) \cdot h=g \cdot h^{\prime}+g^{\prime} \cdot h^{\prime}+g \cdot h+g^{\prime} \cdot h
$$

and hence

$$
\begin{equation*}
g \cdot h+g^{\prime} \cdot h^{\prime}=(-g) \cdot h^{\prime}+\alpha+\left(-g^{\prime}\right) \cdot h=g^{\prime} \cdot h^{\prime}+g \cdot h \tag{e}
\end{equation*}
$$

Remark. We would have obtained the same results if we had replaced the elementary equivalence relations by

$$
\cdots+\left(g+g^{\prime}\right) \times h+\cdots \sim \cdots+g^{\prime} \times h+g \times h+\cdots, \text { etc. }
$$

Theorem 1. $G \circ H$ is an Abelian group; the identity is $0 \cdot 0=g \cdot 0=0 \cdot h$, and the inverse of $g \cdot h$ is

$$
\begin{equation*}
-(g \cdot h)=(-g) \cdot h=g \cdot(-h) \tag{3.4}
\end{equation*}
$$

The distributive laws (1.1) hold.
This follows from the above results. Because of (d), we henceforth assume $G$ and $H$ are Abelian, except in Theorem 11.

Theorem 2. In any $G \circ H$, for any integer $a$,

$$
\begin{equation*}
a(g \cdot h)=a g \cdot h=g \cdot a h \tag{3.5}
\end{equation*}
$$

For instance,

$$
(-2) g \cdot h=(-g-g) \cdot h=-[(g+g) \cdot h]=-[g \cdot h+g \cdot h]=(-2)(g \cdot h) .
$$

Using the distributive laws, we may use summation signs as usual; for instance,

$$
\sum_{i}\left(\sum_{i} a_{i j} g_{j}\right) \cdot h_{i}=\sum_{i} \sum_{j}\left(a_{i j} g_{j} \cdot h_{i}\right)=\sum_{j} \sum_{i}\left(g_{j} \cdot a_{i j} h_{i}\right)=\sum_{j}\left(g_{j} \cdot \sum_{i} a_{i j} h_{i}\right)
$$

4. Examples. A system with both "addition" and "multiplication" may in general be defined by starting with a system or systems, using addition alone,
${ }^{6}$ For a direct proof, we have

$$
\begin{aligned}
g \cdot h & +g^{\prime} \cdot h^{\prime}=g \cdot h+g \cdot h^{\prime}+\left(-g+g^{\prime}\right) \cdot h^{\prime}=g \cdot\left(h+h^{\prime}\right)+\left(g^{\prime}-g\right) \cdot\left(h+h^{\prime}\right) \\
\quad & +\left(g^{\prime}-g\right) \cdot(-h)=\left(g+g^{\prime}-g\right) \cdot\left(h+h^{\prime}\right) \\
& +g^{\prime} \cdot(-h)+(-g) \cdot(-h) \\
& =g^{\prime} \cdot\left(h+h^{\prime}-h\right)+g \cdot h=g^{\prime} \cdot h^{\prime}+g \cdot h
\end{aligned}
$$

forming a tensor product, and defining new equality relations. Specifically, any group pair is an example.
(a) The Abelian groups $G$ and $H$ form a group pair with respect to the group $Z$ if a multiplication $g \times h=z$ is given, satisfying both distributive laws. Any such group pair may be defined by choosing a homomorphism of $G \circ H$ into $Z$. Clearly

$$
\phi\left(\sum g_{i} \cdot h_{i}\right)=\sum g_{i} \times h_{i}
$$

has the required properties. Practically all further examples come under this head.
(b) The most important example of a true tensor product (and the example from which we chose the word "tensor") is probably the following. If $G$ is the tangent vector space at a point of a differentiable manifold, then $G \circ G$ is the space of contravariant tensors of order 2 at the point. (Here $G \circ G$ is not the discrete, but the reduced, or topological, tensor product; see Part II or Part III. The same remark applies to other examples below.) Using also the "conjugate space" $L(G)$ and iterated tensor products gives tensors of all orders (see §11). Of course these spaces are usually defined in terms of coördinate systems in $G$.

Note that in terms of a fixed coördinate system, $G \circ G$ gives: vector times vector equals matrix. For a generalization, see (i) below.
(c) If $G$ in (b) is replaced by Hilbert space, $G \circ G$ is a Hilbert space, ${ }^{7}$ except for the completeness postulate (which could be obtained by completing the space or allowing certain infinite sums in $G \circ G$ ).
(d) The true tensor product $G \circ H$ has also been used in case one of $G, H$ has a finite number of generators, and has been applied in topology. ${ }^{8}$ From the examples (j) and Theorems 3 and 5 below, we may at once determine $G \circ H$ if both $G$ and $H$ have finite sets of generators.

The remaining examples are in general not true tensor products, but come under the heading (a). The general case $G \circ H \rightarrow Z$ does not often occur. The case $G \circ G \rightarrow Z$ appears in (b). The cases $G \circ H \rightarrow H$ and $G \circ G \rightarrow G$ appear in (e) and (g) below.
(e) If $G$ is a group, with "operators" from the group $R$, i.e., $r \cdot g=g$ ', the distributive laws are generally assumed; we have $R \circ G \rightarrow G$. Here one generally lets $R$ be a ring (see $\S 6$ ).
(f) If $G$ is a group and $R$ is a ring, and we wish to form from $G$ a group $G^{*}$

[^2]which "admits" $R$ as operator ring, we need merely use $G^{*}=R \circ G$ (see Theorem 12 below). If we wish to replace $G$ by a group $G^{*}$ in which division by any integer $\neq 0$ is possible and unique, we use $G^{*}=R t \circ G$ (see §8).
(g) If $G$ is a group, any choice of $G \circ G \rightarrow G$ makes $G$ a ring (in general nonassociative), and conversely.
(h) Let $V_{p}, V_{q}$ and $V_{r}$ be linear spaces ( $=$ vector spaces) of dimensions $p$, $q$ and $r$. Set $G=C h_{V_{q}}\left(V_{p}\right)$ ( $=$ group of linear maps of $V_{p}$ into $V_{q}$ ), $H=C h_{V_{r}}$ $\left(V_{q}\right), Z=C h_{V_{r}}\left(V_{p}\right)$. Obviously, we have $G \circ H \rightarrow Z . \quad G, H, Z$, and $G \circ H$ are vector spaces of dimensions $p q, q r, p r$, and $p q^{2} r$. Hence $Z \approx G \circ H$ is possible only if $q=1$, i.e., $V_{q} \approx R l$. In this case it is true, as shown by (10.7) and (10.11) below. If we choose fixed coördinate systems in $V_{p}, V_{q}$ and $V_{r}$, then $G, H$ and $Z$ may be interpreted as groups of matrices.
(i) If $G=H$ is the (additive) group of continuous functions $g(x), 0 \leqq x \leqq 1$, we may interpret $G \circ H$ as a subgroup of the group of continuous functions $z(x, y), 0 \leqq x \leqq 1,0 \leqq y \leqq 1$, with $g \cdot h$ corresponding to $z(x, y)=g(x) h(y)$. As is well known from the theory of integral equations, if we allow infinite sums, we may obtain all continuous functions $z(x, y)$.
(j) Finally, we give some examples of tensor products, using the groups most commonly used as coefficient groups in topology. Let $R t_{1}$ and $R l_{1}$ be $R t$ and $R l$ reduced $\bmod 1$.
\[

$$
\begin{aligned}
& I_{0} \circ G \approx G, \quad I_{\mu} \circ G \approx G_{\mu} \quad \text { (Theorems 7, 8) } \\
& I_{\mu} \circ I_{\nu} \approx I_{(\mu, \nu)}, \\
& I_{\mu} \circ R t \approx I_{\mu} \circ R l \approx I_{\mu} \circ R t_{1} \approx I_{\mu} \circ R l_{1} \approx 0 \quad(\mu>0) \\
& R t \circ R t \approx R t, \quad R t \circ R l \approx R l \circ R l \approx R l, \\
& R t \circ R t_{1} \approx R t \circ R l_{1} \approx R t_{1} \circ R t_{1}, \text { etc. }, \approx 0
\end{aligned}
$$
\]

5. General properties. We first consider commutative and associative properties.

Theorem 3. There is a natural isomorphism $G \circ H \approx H \circ G$, given by

$$
\begin{equation*}
\phi\left(\sum g_{i} \cdot h_{i}\right)=\sum h_{i} \cdot g_{i} \tag{5.1}
\end{equation*}
$$

Theorem 4. There are natural isomorphisms

$$
F \circ(G \circ H) \approx F \circ G \circ H \approx(F \circ G) \circ H,
$$

where $F \circ G \circ H$ is the group of all $\sum f_{i} \cdot g_{i} \cdot h_{i}$, using the three distributive laws. The isomorphisms are given by

$$
\begin{equation*}
\phi\left(\sum f_{i} \cdot g_{i} \cdot h_{i}\right)=\sum\left(f_{i} \cdot g_{i}\right) \cdot h_{i}, \quad \psi\left(\sum f_{i} \cdot g_{i} \cdot h_{i}\right)=\sum f_{i} \cdot\left(g_{i} \cdot h_{i}\right) \tag{5.2}
\end{equation*}
$$

The first theorem is evident; we prove the second, using $\phi$. The definition of $\phi$ is unique, as any equivalence relation in the $\sum f_{i} \cdot g_{i} \cdot h_{i}$ corresponds to one in the $\sum\left(f_{i} \cdot g_{i}\right) \cdot h_{i}$. If $\phi\left(\sum f_{i} \cdot g_{i} \cdot h_{i}\right)=0$, then an equivalence sequence carries
$\sum\left(f_{i} \cdot g_{i}\right) \cdot h_{i}$ into 0 ; a corresponding sequence carries $\sum f_{i} \cdot g_{i} \cdot h_{i}$ into 0 ; hence $\phi$ is an isomorphism into a subgroup of $(F \circ G) \circ H$. Finally, given any

$$
\sum_{i} z_{i} \cdot h_{i}=\sum_{i}\left(\sum_{j} f_{i j} \cdot g_{i j}\right) \cdot h_{i}=\sum_{i, j}\left(f_{i j} \cdot g_{i j}\right) \cdot h_{j}
$$

in $(F \circ G) \circ H, \phi$ carries $\sum f_{i j} \cdot g_{i j} \cdot h_{i}$ into it. This completes the proof.
Next we prove the distributive laws with respect to direct sums and difference groups.

Theorem 5. There is a natural isomorphism

$$
(F \oplus G) \circ H \approx F \circ H \oplus G \circ H,
$$

given by

$$
\begin{align*}
\phi\left[\left(f_{1}, g_{1}\right) \cdot h_{1}+\cdots+\left(f_{n}\right.\right. & \left.\left., g_{n}\right) \cdot h_{n}\right]  \tag{5.3}\\
& =\left(f_{1} \cdot h_{1}+\cdots+f_{n} \cdot h_{n}, g_{1} \cdot h_{1}+\cdots+g_{n} \cdot h_{n}\right)
\end{align*}
$$

To show that $\phi$ is uniquely defined, we have, for instance, as $(f, g)+\left(f^{\prime}, g^{\prime}\right)=$ $\left(f+f^{\prime}, g+g^{\prime}\right)$, $\phi\left[\cdots+(f, g) \cdot h+\left(f^{\prime}, g^{\prime}\right) \cdot h+\cdots\right]$

$$
\begin{aligned}
& =\left(\cdots+f \cdot h+f^{\prime} \cdot h+\cdots, \cdots+g \cdot h+g^{\prime} \cdot h+\cdots\right) \\
& =\left(\cdots+\left(f+f^{\prime}\right) \cdot h+\cdots, \cdots+\left(g+g^{\prime}\right) \cdot h+\cdots\right) \\
& =\phi\left[\cdots+\left\{(f, g)+\left(f^{\prime}, g^{\prime}\right)\right\} \cdot h+\cdots\right] .
\end{aligned}
$$

$\phi$ maps the first group into the whole of the second; for

$$
\begin{equation*}
\phi\left[\left(f_{1}, 0\right) \cdot h_{1}+\cdots+\left(0, g_{1}\right) \cdot h_{1}^{\prime}+\cdots\right]=\left(f_{1} \cdot h_{1}+\cdots, g_{1} \cdot h_{1}^{\prime}+\cdots\right) \tag{5.4}
\end{equation*}
$$

Clearly $\phi$ is a homomorphism. Now suppose $\phi(\alpha)=0$; let $\alpha$ be given as in (5.3). First, we may transform $\alpha$ into the form of the left side of (5.4). For each half of the right side of (5.3), there is an equivalence sequence carrying it into 0 . There are corresponding sequences acting on the left side of (5.4), which shows that $\alpha=0$. Hence $\phi$ is an isomorphism.

Theorem 6. If $G^{\prime}$ is a subgroup of $G$, there is a natural isomorphism

$$
\left(G \ominus G^{\prime}\right) \circ H \approx G \circ H \ominus \sum^{*}\left(G^{\prime} \cdot H\right)
$$

given as follows. If $\psi$ and $\Psi$ are the natural homomorphisms of $G$ into $G \Theta G^{\prime}$ and of $G \circ H$ into $G \circ H \ominus \sum^{*}\left(G^{\prime} \cdot H\right)$, we set

$$
\begin{equation*}
\phi\left[\psi\left(g_{1}\right) \cdot h_{1}+\cdots+\psi\left(g_{n}\right) \cdot h_{n}\right]=\Psi\left(g_{1} \cdot h_{1}+\cdots+g_{n} \cdot h_{n}\right) . \tag{5.5}
\end{equation*}
$$

By Theorem 3, there is a similar relation with $G$ and $H$ interchanged.
To show that $\phi$ is uniquely defined, suppose first that $\psi\left(g_{1}\right)=\psi\left(\bar{g}_{1}\right)$. Then $\bar{g}_{1}=g_{1}+g^{\prime}\left(g^{\prime}\right.$ in $\left.G^{\prime}\right)$, and

$$
\Psi\left(\bar{g}_{1} \cdot h_{1}+\cdots\right)=\Psi\left(g_{1} \cdot h_{1}+\cdots\right)+\Psi\left(g^{\prime} \cdot h_{1}\right)=\Psi\left(g_{1} \cdot h_{1}+\cdots\right) .
$$

The rest of the proof is like previous proofs. For instance, if the element (5.5) vanishes, then $\sum g_{i} \cdot h_{i}$ is in $\sum^{*}\left(G^{\prime} \cdot H\right)$, and hence may be transformed into the form $\sum g_{i}^{\prime} \cdot h_{i}^{\prime}\left(g_{i}^{\prime}\right.$ in $\left.G^{\prime}\right)$. The same transformations may be carried out on the left side of (5.5); as $\psi\left(g_{i}^{\prime}\right)=0$, this gives $\sum \psi\left(g_{i}\right) \cdot h_{i}=0$.

Remark. $\sum^{*}\left(G^{\prime} \cdot H\right)$ is perhaps "smaller" than $G^{\prime} \circ H$; for instance, if $G=I_{0}$, $G^{\prime}=2 G, H=I_{2}$, then $G^{\prime} \circ H \approx I_{2}, \sum^{*}\left(G^{\prime} \cdot H\right) \approx 0$. But there is a natural homomorphism of $G^{\prime} \circ H$ onto the whole of $\sum^{*}\left(G^{\prime} \cdot H\right)$, clearly. Compare Theorem 28, Part II.

Theorem 7. There is a natural isomorphism $I_{0} \circ G \approx G$, given by

$$
\begin{equation*}
\phi\left(\sum a_{i} \cdot g_{i}\right)=\sum a_{i} g_{i} \tag{5.6}
\end{equation*}
$$

The proof is like previous proofs. Note that we have a normal form for elements of $I_{0} \circ G$ : if we use Theorem 2,

$$
\begin{equation*}
\sum a_{i} \cdot g_{i}=\sum 1 \cdot a_{i} g_{i}=1 \cdot \sum a_{i} g_{i}=1 \cdot g^{\prime} \tag{5.7}
\end{equation*}
$$

The expression of an element in the normal form is unique, by the theorem.
Theorem 8. There is a natural isomorphism $I_{\mu} \circ G \approx G_{\mu}$, given by ${ }^{9}$

$$
\begin{equation*}
\phi\left(\sum_{i} a_{\mu}^{i} \cdot g^{i}\right)=\sum_{i} a^{i} g_{\mu}^{i} \tag{5.8}
\end{equation*}
$$

Using Theorems 6 and 7, we see easily that the following isomorphism is the one given by the theorem:

$$
\begin{aligned}
I_{\mu} \circ G=\left(I_{0} \ominus \mu I_{0}\right) \circ G \approx & I_{0} \circ G \ominus \sum^{*}\left(\mu I_{0} \cdot G\right) \\
& =I_{0} \circ G \ominus \sum^{*}\left(I_{0} \cdot \mu G\right) \approx I_{0} \circ(G \ominus \mu G) \approx G_{\mu}
\end{aligned}
$$

Theorem 9. If $G$ is completely divisible and every element of $H$ is of finite order, then $G \circ H \approx 0$.
For if $m h=0$, then $g \cdot h=m g^{\prime} \cdot h=g^{\prime} \cdot m h=0$.
Theorem 10. If $G^{\prime}$ and $H^{\prime}$ are subgroups of the nullifiers of $H$ and $G$ in $G$ and $H$, respectively, then there are natural isomorphisms

$$
G \circ H \approx\left(G \ominus G^{\prime}\right) \circ H \approx G \circ\left(H^{\prime} \ominus H\right) \approx\left(G \ominus G^{\prime}\right) \circ\left(H \ominus H^{\prime}\right)
$$

if $\phi$ and $\psi$ are the natural isomorphisms of $G$ into $G \ominus G^{\prime}$ and of $H$ into $H \ominus H^{\prime}$, these are given by

$$
\sum g_{i} \cdot h_{i} \approx \sum \phi\left(g_{i}\right) \cdot h_{i} \approx \sum g_{i} \cdot \psi\left(h_{i}\right) \approx \sum \phi\left(g_{i}\right) \cdot \psi\left(h_{i}\right) .
$$

First, applying Theorem 6, we find, as $G^{\prime} \cdot H=0$,

$$
G \circ H \approx G \circ H \ominus \sum^{*}\left(G^{\prime} \cdot H\right) \approx\left(G \ominus G^{\prime}\right) \circ H, \text { etc. }
$$

Next, for any $h^{\prime}$ in $H^{\prime}, \phi(g) \cdot h^{\prime}$ corresponds to $g \cdot h^{\prime}=0$ in the first isomorphism above; hence $\left(G \ominus G^{\prime}\right) \cdot H^{\prime}=0$, and

$$
\left(G \ominus G^{\prime}\right) \circ H \approx\left(G \ominus G^{\prime}\right) \circ H \Theta \sum^{*}\left(\left(G \ominus G^{\prime}\right) \cdot H^{\prime}\right) \approx\left(G \ominus G^{\prime}\right) \circ\left(H \ominus H^{\prime}\right)
$$

[^3]We end by showing that the discrete tensor product of any two groups, not necessarily Abelian, is isomorphic to the discrete tensor product of the two groups "made Abelian".

Theorem 11. Let $G$ and $H$ be any two groups, and let $G^{\prime}$ and $H^{\prime}$ be their commutator subgroups. Then there is a natural isomorphism

$$
G \circ H \approx\left(G \ominus G^{\prime}\right) \circ\left(H \Theta H^{\prime}\right)
$$

Because of Theorem 10, we need merely show that any commutator is in the nullifier of the other group; this follows at once from §3, (d).
6. Sets, groups, rings, operators. If $A$ and $B$ are two sets of elements, we may define their (discrete) tensor product as the set of all symbols $\pm a_{1} \cdot b_{1} \pm \ldots$ $\pm a_{n} \cdot b_{n}$, with the obvious definition of + , which we assume commutative. This is a free group, generated by all $a \cdot b$; if $A$ and $B$ have $m$ and $n$ elements, respectively, then $A \circ B$ has $m n$ generators.

If $G$ is an Abelian group and $A$ is a set of elements, their tensor product is the set of all $\sum g_{i} \cdot a_{i}$, with the distributive law as in (3.1), postulating that + is commutative, and $0 \cdot a+g \cdot a^{\prime}=g \cdot a^{\prime}$. This is the "group of all linear forms over elements of $A$, with coefficients in $G^{\prime \prime}$. An example is given by the groups of chains used in topology.

We shall say an Abelian group $G$ admits the ring $R$ as operator ring, or admits $R$ simply, if $R$ has a unit 1 , and $r g=g^{\prime}$ is defined satisfying

$$
\begin{array}{ll}
r\left(g+g^{\prime}\right)=r g+r g^{\prime}, & \left(r+r^{\prime}\right) g=r g+r^{\prime} g  \tag{6.1}\\
r\left(r^{\prime} g\right)=\left(r r^{\prime}\right) g \text { or }\left(r^{\prime} r\right) g, & 1 g=g
\end{array}
$$

We call $R$ a left or right operator according as we use $\left(r r^{\prime}\right) g$ or $\left(r^{\prime} r\right) g$ in the third relation. In the second case, we might write $g r$ in place of $r g$, obtaining $\left(g r^{\prime}\right) r=$ $g\left(r^{\prime} r\right)$. Suppose, for definiteness, we write $r[g]$ instead of $r g$. Then a ring can operate on itself in both ways, using

$$
\begin{equation*}
r\left[r^{\prime}\right]=r r^{\prime} \quad \text { and } \quad r\left[r^{\prime}\right]=r^{\prime} r . \tag{6.2}
\end{equation*}
$$

The associative law $r\left[r^{\prime}\left[r^{\prime \prime}\right]\right]=\left(r\left[r^{\prime}\right]\right)\left[r^{\prime}\right]$ holds in either case.
If $G$ and $H$ both admit $R$, to left or right, we say an isomorphism $\phi$ between $G$ and $H$ is an operator isomorphism if $\phi(r g)=r \phi(g)$; we use $\approx$ again, and say $\phi$ preserves the operator.

Theorem 12. If $R$ is a ring with unit, and we define $R \circ G$, considering $R$ as a group under addition, then $R \circ G$ admits $R$ to left or right, under the definitions

$$
\begin{equation*}
r\left(\sum r_{i} \cdot g_{i}\right)=\sum r r_{i} \cdot g_{i} \text { or } \quad \sum r_{i} r \cdot g_{i} \tag{6.3}
\end{equation*}
$$

The proof is simple. The following theorem is a generalization.
Theorem 13. If $G$ admits $R$ to left or to right, then so does any tensor product $G \circ H$ or $H \circ G$, under the definition

$$
\begin{equation*}
r\left(\sum g_{i} \cdot h_{i}\right)=\sum r g_{i} \cdot h_{i}, \quad r\left(\sum h_{i} \cdot g_{i}\right)=\sum h_{i} \cdot r g_{i} \tag{6.4}
\end{equation*}
$$

Suppose $G$ and $H$ both admit $R$, each to one side. Then we define the reduced tensor product $G \circ^{\prime} H$ with respect to $R$ as follows. Take the tensor product $G \circ H$, and define a new relation

$$
\begin{equation*}
r g \cdot h=g \cdot r h \tag{6.5}
\end{equation*}
$$

$G \circ^{\prime} H$ is the group thus formed; it is the difference group of $G \circ H$ with the group generated by all $r g \cdot h-g \cdot r h$.

Theorem 14. If $G$ admits $R$ to the left, then there is a natural operator isomorphism

$$
R \circ^{\prime} G \approx G
$$

letting $R$ act on itself to the right and on $R \circ^{\prime} G$ to the left, given by

$$
\begin{equation*}
\phi\left(\sum r_{i} \cdot g_{i}\right)=\sum r_{i} g_{i} . \tag{6.6}
\end{equation*}
$$

Here, (6.5) is replaced by

$$
r r^{\prime} \cdot g=r^{\prime}[r] \cdot g=r \cdot r^{\prime}[g]=r \cdot r^{\prime} g
$$

To show that $\phi$ is uniquely defined, we have for instance

$$
\phi\left(r r^{\prime} \cdot g\right)=\left(r r^{\prime}\right) g=r\left(r^{\prime} g\right)=\phi\left(r \cdot r^{\prime} g\right)
$$

$\phi$ is a homomorphism into the whole of $G$; for $\phi(1 \cdot g)=1 g=g$. It preserves the operator, for

$$
\begin{aligned}
\phi\left(r\left(\sum r_{i} \cdot g_{i}\right)\right)=\phi\left(\sum r r_{i} \cdot g_{i}\right)=\sum\left(r r_{i}\right) g_{i}=\sum r & \left(r_{i} g_{i}\right) \\
& =r\left(\sum r_{i} g_{i}\right)=r \phi\left(\sum r_{i} \cdot g_{i}\right)
\end{aligned}
$$

Finally, $\phi$ is (1-1). For if $\phi\left(\sum r_{i} \cdot g_{i}\right)=\sum r_{i} g_{i}=0$, then

$$
\sum r_{i} \cdot g_{i}=\sum 1 \cdot r_{i} g_{i}=1 \cdot \sum r_{i} g_{i}=1 \cdot 0=0
$$

The theorem clearly holds with "right" and "left" interchanged.
Suppose $R$ and $S$ are rings. ${ }^{10}$ Then we can make $R \circ S$ a ring in four different ways, namely,

$$
\begin{gather*}
(r \cdot s)\left(r^{\prime} \cdot s^{\prime}\right)=r r^{\prime} \cdot s s^{\prime} \quad \text { or } \quad r r^{\prime} \cdot s^{\prime} s, \text { etc. } \\
\left(\sum r_{i} \cdot s_{i}\right)\left(\sum r_{j}^{\prime} \cdot s_{j}^{\prime}\right)=\sum \sum\left(r_{i} \cdot s_{i}\right)\left(r_{j}^{\prime} \cdot s_{j}^{\prime}\right) \tag{6.7}
\end{gather*}
$$

The uniqueness of the definition is easily established. The associative and distributive laws hold. If $R$ and $S$ have units $1_{R}$ and $1_{S}$, then so has $R \circ S$, namely, $1_{R} \cdot 1_{s}$.

We shall not discuss the questions of zero-divisors or of fields.

## 7. Rational multipliers and tensor products.

Definition. For any rational number $r, r=a / b,(a, b)=1$, and any $A \subset G$

[^4](including $A=g$ ), we let $r A$ be the set of all elements $g^{\prime}$ such that $b g^{\prime}=a g$, $g$ in $A$. This agrees with the definition of $a A$ and with the natural definition of $(1 / a) A$. Then some of the formal properties of rational numbers as multipliers hold. In particular, some elements can be divided by certain integers. Division by integers, when it exists, is unique if and only if $G$ has no elements $\neq 0$ of finite order. For if $g^{\prime}$ and $g^{\prime \prime}$ are in $(1 / a) g, g^{\prime} \neq g^{\prime \prime}$, then $a\left(g^{\prime}-g^{\prime \prime}\right)=g-g$ $=0$, so that $g^{\prime}-g^{\prime \prime}$ is of finite order; if $g \neq 0$ is of finite order $a$, then $(1 / a) 0$ is not unique. We shall say $G$ has unique division if it is completely divisible and has no elements $\neq 0$ of finite order. Because of Theorem 15 below, we may then multiply by rational numbers in such a group, and all formal laws will hold.

The only theorem we will need in $\S 8$ is the following.
Theorem 15. The following three statements are equivalent:
(a) $G$ admits Rt as operator ring; we shall write $r[g]$.
(b) G has unique division.
(c) For each rational $r$ and each $g$ in $G, r g$ is a unique element of $G$.

Further, G can admit Rt in at most one way; if it does, then $r g=r[g]$.
First, if $G$ admits $R t$, then $G$ has no elements of finite order. For, note first that (for $a>0$, and hence for $a \leqq 0$ ),

$$
\begin{equation*}
a[g]=(1+\cdots+1)[g]=1[g]+\cdots+1[g]=a g \tag{*}
\end{equation*}
$$

Now if $a g=0, a \neq 0$, then $a[g]=a g=0=a 0=a[0]$; hence

$$
g=1[g]=\left(\frac{1}{a} a\right)[g]=\frac{1}{a}[a[g]]=\frac{1}{a}[a[0]]=1[0]=0 .
$$

Next, if (a) holds, then for each integer $a \neq 0$ and each $g$ in $G, g^{\prime}=(1 / a)[g]$ exists, and $a g^{\prime}=a\left[g^{\prime}\right]=g$; hence (b) holds. (b) clearly implies (c). If (c) holds, then setting $r[g]=r g$ gives (a).

Finally, if two operations $r[g]$ and $r\{g\}$ are defined, then they agree; for by $\left({ }^{*}\right)$,

$$
b\left(\frac{a}{b}[g]\right)=\left(b \frac{a}{b}\right)[g]=a[g]=a g=b\left(\frac{a}{b}\{g\}\right)
$$

as $G$ can have no elements of finite order, $(a / b)[g]=(a / b)\{g\}$. Also

$$
b\left(\frac{a}{b}[g]\right)=a[g]=a g=b\left(\frac{a}{b} g\right)
$$

and hence $r[g]=r g$.
Before considering tensor products, we consider some divisibility properties in general groups. Let $\delta_{r}$ denote the denominator of $r ; \delta_{r}=b$ if $r=a / b,(a, b)=1$.

Lemma 1. If rg is not void, then $\delta_{r} \mid g$, and conversely.
For if $r=a / b, b g^{\prime}=a g$, and $p a+q b=1$, then

$$
b\left(q g+p g^{\prime}\right)=q b g+p a g=g
$$

The converse is clear.

Lemma 2. If $(a, b)=1$, then

$$
\begin{equation*}
\frac{a}{b} A=a\left(\frac{1}{b} A\right)=\frac{1}{b}(a A) \tag{7.1}
\end{equation*}
$$

To prove the first relation, the elements of $a((1 / b) A)$ are all $g^{\prime}, g^{\prime}=a g^{*}, g^{*}$ in $(1 / b) A$, i.e., $b g^{*}=g$ in $A$; then $b g^{\prime}=a g$, and as $(a, b)=1, g^{\prime}$ is in $(a / b) A$. Conversely, if $g^{\prime}$ is in $(a / b) A$, then $b g^{\prime}=a g(g$ in $A)$. Choose $p, q$ so that $p a+q b=1$, and set $g^{*}=q g+p g^{\prime}$. Then

$$
b g^{*}=q b g+p a g=g, \quad a g^{*}=q b g^{\prime}+p a g^{\prime}=g^{\prime}
$$

so that $g^{*}$ is in $(1 / b) A$ and $g^{\prime}$ is in $a g^{*} \subset a((1 / b) A)$. The second relation is clear.
Lemma 3. For any integers $a$ and $b$,

$$
\begin{equation*}
\frac{1}{a}\left(\frac{1}{b} A\right)=\frac{1}{a b} A, \quad a\left(\frac{1}{a} A\right) \subset A, \quad \frac{1}{a}(a A) \supset A \tag{7.2}
\end{equation*}
$$

The proof is simple.
We turn now to tensor products.
Lemma 4. If $\delta_{r} \mid g$ and $\delta_{r} \mid h$, then

$$
\begin{equation*}
g^{\prime} \cdot h=g \cdot h^{\prime} \quad \text { for any } g^{\prime} \text { in rg and any } h^{\prime} \text { in } r h . \tag{7.3}
\end{equation*}
$$

Set $r=a / b,(a, b)=1$. If

$$
b g^{\prime}=a g, \quad g=b g^{*}, \quad b h^{\prime}=a h, \quad h=b h^{*}
$$

then

$$
\begin{aligned}
& g \cdot h^{\prime}=b g^{*} \cdot h^{\prime}=g^{*} \cdot b h^{\prime}=g^{*} \cdot a h=g^{*} \cdot a b h^{*}=a b g^{*} \cdot h^{*}=a g \cdot h^{*} \\
&=b g^{\prime} \cdot h^{*}=g^{\prime} \cdot b h^{*}=g^{\prime} \cdot h .
\end{aligned}
$$

Example. If $\delta_{r} \mid h$ is false, $r g \cdot h$ may not be uniquely defined. For if $G=H=$ $I_{2}, g=0_{2}, h=1_{2}$, then $G \circ H \approx I_{2}$, and $\frac{1}{2} g \cdot h$ contains both $0_{2}$ and $1_{2}$.

Theorem 16. If $\delta_{r} \mid A$ and $\delta_{r} \mid B$, then

$$
\begin{equation*}
r A \cdot B=A \cdot r B \tag{7.4}
\end{equation*}
$$

if $A$ and $B$ are single elements, so is $r A \cdot B$.
This follows from Lemmas 1 and 4.
Remark. $\quad r(g \cdot h)$ may be $\neq r g \cdot h$. For example, if $G=H=I_{2}, g=h=0_{2}$, $r=\frac{1}{2}$, then $r g \cdot h=0_{2}$, while $r(g \cdot h)$ contains both $0_{2}$ and $1_{2}$. However,

$$
\begin{equation*}
r(A \cdot B) \supset r A \cdot B \tag{7.5}
\end{equation*}
$$

for if $r=a / b,(a, b)=1, g$ in $A, h$ in $B, b g^{\prime}=a g$, so that $g^{\prime} \cdot h$ is in $r A \cdot B$, then

$$
b\left(g^{\prime} \cdot h\right)=b g^{\prime} \cdot h=a g \cdot h=a(g \cdot h) \text { is in } a(A \cdot B)
$$

so that $g^{\prime} \cdot h$ is in $r(A \cdot B)$.

Lemma 5. If $b \mid A$ and $b \mid B$, then

$$
\begin{equation*}
\frac{1}{b}(a A) \cdot B=\frac{a}{b} A \cdot B=a\left(\frac{1}{b} A\right) \cdot B=A \cdot \frac{1}{b}(a B)=A \cdot \frac{a}{b} B=A \cdot a\left(\frac{1}{b} B\right) \tag{7.6}
\end{equation*}
$$

if $A$ and $B$ are single elements, so is the above.
Say $(a, b)=k, a=a^{\prime} k, b=b^{\prime} k$; then $\left(a^{\prime}, b^{\prime}\right)=1$. To prove the first relation, we use Lemmas 2 and 3 and Theorem 16, and the fact $b \mid a A$ :

$$
\begin{gathered}
\frac{1}{b}(a A) \cdot B=\frac{1}{b^{\prime}}\left(\frac{1}{k}\left(k\left(a^{\prime} A\right)\right)\right) \cdot B \supset \frac{1}{b^{\prime}}\left(a^{\prime} A\right) \cdot B=\frac{a^{\prime}}{\overline{b^{\prime}}} A \cdot B=\frac{a}{b} A \cdot B \\
\frac{1}{b}(a A) \cdot B=A \cdot a\left(\frac{1}{b} B\right)=A \cdot a^{\prime}\left(k\left(\frac{1}{k}\left(\frac{1}{b^{\prime}} B\right)\right)\right) \subset A \cdot a^{\prime}\left(\frac{1}{b^{\prime}} B\right)=\frac{a}{b} A \cdot B .
\end{gathered}
$$

From these the relation follows. The other relations are consequences of this one or are easily proved. The last statement follows from Theorem 16.

Theorem 17. If $\delta_{r} \delta_{r^{\prime}} \mid A$ and $\delta_{r} \delta_{r^{\prime}} \mid B,{ }^{11}$ then

$$
\begin{equation*}
r\left(r^{\prime} A\right) \cdot B=\left(r r^{\prime}\right) A \cdot B=A \cdot\left(r r^{\prime}\right) B, \text { etc.; } \tag{7.7}
\end{equation*}
$$

if $A$ and $B$ are single elements, so is the above.
Say $r=a / b, r^{\prime}=c / d,(a, b)=(c, d)=1 . \quad$ As $b d \mid c A$, etc.,

$$
\begin{aligned}
r\left(r^{\prime} A\right) \cdot B=a\left(\frac{1}{b}\left(\frac{1}{d}(c A)\right)\right) \cdot B=\frac{1}{b d}(c A) \cdot a B=a c & \left(\frac{1}{b d} A\right) \cdot B \\
& =\frac{a c}{b d} A \cdot B=\left(r r^{\prime}\right) A \cdot B, \text { etc. }
\end{aligned}
$$

8. The tensor product $R t \circ G$. First note that, if $F$ is any completely divisible group (in particular, $R t$ ), then in studying $F \circ G$, we could assume that $G$ has no elements $\neq 0$ of finite order. For otherwise, let $G^{\prime}$ be the subgroup of elements of finite order of $G$. As $G^{\prime}$ is in the nullifier of $F, \sum^{*}\left(F \cdot G^{\prime}\right)=0$ (see Theorem 9); hence, by Theorem 10,

$$
F \circ G \approx F \circ\left(G \ominus G^{\prime}\right)
$$

Thus we may replace $G$ by $G \ominus G^{\prime}$, which has no elements $\neq 0$ of finite order.
Theorem 18. In Rt $\circ G$, each element may be written in the form $(1 / a) \cdot g$. If $G$ has no elements $\neq 0$ of finite order, then $r \cdot g=0$ if and only if $r=0$ or $g=0$.

First,

$$
\sum r_{i} \cdot g_{i}=\sum \frac{a_{i}}{a} \cdot g_{i}=\frac{1}{a} \cdot \sum a_{i} g_{i}=\frac{1}{a} \cdot g
$$

Next, suppose we have an equivalence sequence reducing $r \cdot g$ to $0 \cdot 0$. In all terms occurring, there is a least common denominator $c$. Multiplying every-
${ }^{11}$ Possibly this hypothesis can be weakened.
thing by $c$ gives an equivalence sequence, which may be interpreted as a sequence in $I_{0} \circ G$, or again, in $G$ itself. Hence, if $r=a / b$, we have $(c a / b) g=0$. If $r \neq 0$, then $c a / b \neq 0$, and as $G$ has no elements of finite order, $g=0$.

Theorem 19. Rt。G has unique division.
This follows from Theorems 12 and 15.
Theorem 20. There is an isomorphism $G \approx R t \circ G$, given by $\phi\left(\sum r_{i} \cdot g_{i}\right)=$ $\sum r_{i} g_{i}$, if and only if $G$ has unique division.

This is an extension of Theorem 15. One half follows from Theorem 19; the other half is clear.

Theorem 21. If $G$ has no elements $\neq 0$ of finite order, then $R t \circ G$ is the smallest completely divisible group containing $G$. That is, if $H$ is completely divisible and contains a subgroup $H_{1} \approx G$, then it contains a subgroup $H_{2} \approx R t \circ G$.

Let $H^{\prime}$ be the subgroup of elements of finite order of $H$. Clearly $H^{\prime}$ is completely divisible; hence we may write $H=H^{\prime} \oplus H^{\prime \prime} .^{12} \quad$ For any $h=h^{\prime}+h^{\prime \prime}$, write $h^{\prime}=\phi(h), h^{\prime \prime}=\psi(h)$; then $\phi$ and $\psi$ are homomorphisms. Set $H_{1}^{\prime \prime}=$ $\psi\left(H_{1}\right)$; then $H_{1}^{\prime \prime} \approx G$. For if $\psi\left(h_{1}\right)=0\left(h_{1}\right.$ in $\left.H_{1}\right)$, then $h_{1}$ is in $H^{\prime}$, and hence is of finite order; but $h_{1}$ is in $H_{1} \approx G$, which gives $h_{1}=0$.

Let $H_{2}$ be the subgroup of $H^{\prime \prime}$ containing all elements with multiples in $H_{1}{ }^{\prime \prime}$. $H_{2}$ is completely divisible. For given $h$ in $H_{2}$ and an integer $a \neq 0$, choose $h^{*}$ in $H$ so that $a h^{*}=h$, and set $h_{1}=\psi\left(h^{*}\right)$. Then $h_{1}$ is in $H^{\prime \prime}$, and as $h$ is in $H^{\prime \prime}$,

$$
a h_{1}=a \psi\left(h^{*}\right)=\psi\left(a h^{*}\right)=\psi(h)=h ;
$$

hence $h_{1}$ is in $H_{2}$. As $H^{\prime \prime}$ has no elements $\neq 0$ of finite order, neither has $H_{2}$; hence $H_{2}$ has unique division.

Let $\theta$ be the isomorphism of $G$ into $H_{1}^{\prime \prime}$. As $r h$ is uniquely defined for $h$ in the group $H_{2}$ (Theorem 15), and clearly obeys $\left(r+r^{\prime}\right) / h=r h+r^{\prime} h, r\left(h+h^{\prime}\right)=$ $r h+r h^{\prime}$, we may set

$$
\Theta\left(\sum r_{i} \cdot g_{i}\right)=\sum r_{i} \theta\left(g_{i}\right)
$$

defining a homomorphism of $R t \circ G$ into $H_{2}$. Suppose $\Theta(\alpha)=0$. If $\alpha=$ $(1 / a) \cdot g$ (Theorem 18), then $\Theta(\alpha)=(1 / a) \theta(g)=0$. Multiplying by $a$ gives $\theta(g)$ $=0$, and hence $g=0$, and $\alpha=0$, as $\theta$ is an isomorphism. Hence $\Theta$ is (1-1). For any $h$ in $H_{2}$, we may take $a$ so that $a h$ is in $H_{1}^{\prime \prime}$; then for some $g, a h=\theta(g)$ $=\Theta(1 \cdot g)$, and $h=\Theta((1 / a) \cdot g)$; hence $\Theta$ is an isomorphism, and the theorem is proved.
9. Tensor products and character groups. In some cases, the group $C h_{H}(G)$ of homomorphisms of $G$ into $H$ can be expressed in terms of the two groups $H$ and $C h_{I_{0}}(G)$, by (9.1). See also Theorem 25 of Part II. We remark in passing that $C h_{H}(G)$ and $G$ form a group pair with respect to $H$, with the definition $\Phi\left(\sum \phi_{i} \cdot g_{i}\right)=\sum \phi_{i}\left(g_{i}\right)\left(\phi_{i}\right.$ in $C h_{H}(G), g_{i}$ in $\left.G\right)$.

[^5]Theorem 22. ${ }^{13}$ There is a natural isomorphism

$$
\begin{equation*}
C h_{I_{0}}(G) \circ H \approx Z \subset C h_{B}(G) \tag{9.1}
\end{equation*}
$$

defined as follows. For $u_{i}$ in $C h_{I_{0}}(G)$ and $h_{i}$ in $H$,

$$
\begin{equation*}
\Phi\left(\sum u_{i} \cdot h_{i} ; g\right)=\sum u_{i}(g) h_{i} \tag{9.2}
\end{equation*}
$$

If either $G$ or $H$ is a free group with a finite number of generators, then $Z=C h_{H}(G)$.
It is clear that the definition of $\Phi$ is unique, and $\Phi$ is a homomorphism. We must show that it is (1-1). Suppose the element (9.2) equals 0. Say the sum contains $n$ terms. Let $A=I_{0} \oplus \cdots \oplus I_{0}$ be the group of all $n$-tuples ( $a_{1}, \cdots$, $a_{n}$ ) of integers, and let $A^{\prime}$ be the subgroup of all ( $a_{1}, \cdots, a_{n}$ ) in $A$ for which $\sum a_{i} h_{i}=0$. We may choose a base

$$
\alpha_{1}, \cdots, \alpha_{n} ; \quad \alpha_{i}=\left(a_{i 1}, \cdots, a_{i n}\right)
$$

in $A$ and integers $p_{1}, \cdots, p_{m}(m \leqq n)$ such that

$$
p_{1} \alpha_{1}, \cdots, p_{m} \alpha_{m}
$$

form a base in $A^{\prime} .^{14}$ For each $g$, let $u(g)$ be the element ( $\left.u_{1}(g), \cdots, u_{n}(g)\right)$ of $A$; as $\sum u_{i}(g) h_{i}=0, u(g)$ is in $A^{\prime}$. Hence, for each $g$, there is a uniquely defined set of numbers $\rho_{1}(g), \cdots, \rho_{m}(g)$ such that

$$
u(g)=\sum_{j=1}^{m} \rho_{j}(g) p_{i} \alpha_{j}
$$

hence

$$
u_{i}=\sum_{j=1}^{m} p_{j} a_{i i} \rho_{j} .
$$

As the $u_{i}(g)$ are homomorphisms, so are $u(g)$ and the $\rho_{i}(g)$; the $\rho_{i}(g)$ are in $C h_{I_{0}}(G)$. Set

$$
\bar{h}_{i}=\sum_{k=1}^{n} a_{i k} h_{k} \quad(i=1, \cdots, m)
$$

then

$$
p_{i} \bar{h}_{i}=\sum_{k=1}^{n} p_{i} a_{i k} h_{k}=0 \quad(i=1, \cdots, m)
$$

by the choice of the $\alpha_{i}$ and $p_{i}$. Hence, using the distributive laws in $C h_{I_{0}}(G) \circ H$,

$$
\begin{aligned}
\sum_{i=1}^{n} u_{i} \cdot h_{i}=\sum_{i=1}^{n}\left(\sum_{j=1}^{m} p_{j} a_{j i} \rho_{j}\right) \cdot h_{i}=\sum_{j=1}^{m}\left(\rho_{i} \cdot p_{i} \sum_{i=1}^{n}\right. & \left.a_{j i} h_{i}\right) \\
& =\sum_{j=1}^{m}\left(\rho_{j} \cdot p_{j} \bar{h}_{j}\right)=\sum_{j=1}^{m}\left(\rho_{j} \cdot 0\right)=0
\end{aligned}
$$

as required.
${ }^{18}$ Compare Theorem 25.
${ }^{14}$ See, for example, Alexandroff-Hopf, loc. cit., p. 566.

Now suppose $H$ has a base $\bar{h}_{1}, \cdots, \bar{h}_{n}$, so any $h$ may be written uniquely $\sum a_{i} \bar{h}_{i}$. Let $\phi$ be any homomorphism of $G$ into $H$; then we may write

$$
\phi(g)=\sum u_{i}(g) \bar{h}_{i},
$$

and the $u_{i}(g)$ are elements of $C h_{I_{0}}(G)$. Also

$$
\Phi\left(\sum u_{i} \cdot \bar{h}_{i} ; g\right)=\sum u_{i}(g) \bar{h}_{i}=\phi(g)
$$

so $\Phi$ maps $C h_{I_{0}}(G) \circ H$ into the whole of $C h_{H}(G)$.
Suppose finally that $G$ has a base $\bar{g}_{1}, \cdots, \bar{g}_{n}$. Let $\bar{u}_{i}(g)$ be the element of $C h_{I_{0}}(G)$ defined by $\bar{u}_{i}\left(\bar{g}_{i}\right)=1, \bar{u}_{i}\left(\bar{g}_{j}\right)=0(j \neq i)$. Take any homomorphism $\phi$ of $G$ into $H$. Then for any $g=\sum a_{i} \bar{g}_{i}, \bar{u}_{i}(g)=a_{i}$, and

$$
\phi(g)=\sum a_{i} \phi\left(\bar{g}_{i}\right)=\sum \bar{u}_{i}(g) \phi\left(\bar{g}_{i}\right) ;
$$

hence, setting $h_{i}=\phi\left(\bar{g}_{i}\right)$,

$$
\Phi\left(\sum \bar{u}_{i} \cdot h_{i} ; g\right)=\sum \bar{u}_{i}(g) \phi\left(\bar{g}_{i}\right)=\phi(g) .
$$

This completes the proof.
Examples. Suppose $G=H=I_{2}$. Then $C h_{H}(G)$ has two elements, while $C h_{I_{0}}(G) \circ H$ has only one. Again, let $G$ be the additive group of triadic rational numbers (all numbers of the form $a / 3^{b}$ ), and set $H=I_{2}$. There are two elements in $C h_{H}(G)$, determined by $\phi(1)=0_{2}$ and $\phi(1)=1_{2}$; but there is only one element in $C h_{I_{0}}(G) \circ H$.

## II. Linear spaces

10. Products, finite dimensional spaces. A linear space, or vector space, $G$, is an Abelian ${ }^{15}$ group which admits the real numbers $R l$ as operators (see §6). Let $G\left(g_{1}, \cdots, g_{m}\right)$ be the subspace of $G$ generated by $g_{1}, \cdots, g_{m}$, i.e., all $\sum a_{i} g_{i}\left(a_{i}\right.$ real). If such a set generates $G$ itself, then let $g_{1}, \cdots, g_{m}$ be such a set with the least number of elements. Then these elements form a base for $G$, and $G$ is of dimension $m$.

In any finite dimensional linear space $G$, with a base $g_{1}, \cdots, g_{m}$, we may introduce a natural topology by defining neighborhoods $U(\epsilon)$ of 0 for each $\epsilon>0$, consisting of all $\sum a_{i} g_{i}$ with $\sum a_{i}^{2}<\epsilon^{2}$. The topology is independent of the choice of a base. In this topology, the operation $a g$ is continuous in both variables.

In the tensor product $G \circ H$, we clearly wish to have

$$
\begin{equation*}
a(g \cdot h)=a g \cdot h=g \cdot a h \quad(a \text { in } R l) \tag{10.1}
\end{equation*}
$$

hence we use the reduced tensor product (see (6.4)), but call it the tensor product simply. Without this, we would have for instance in $R l, \sqrt{2} \cdot 1 \neq 1 \cdot \sqrt{2}$. Further, if we assume that $g \cdot h$ is continuous, then (10.1) follows. To show this, the last statement in Theorem 15, and Theorem 16, show that $b g \cdot h=g \cdot b h$ for any rational $b$. Letting $b \rightarrow a$ gives the result.

[^6]We assume in the rest of $\S 10$ that $G$ and $H$ have bases $\bar{g}_{1}, \ldots, \bar{g}_{m}$ and $\bar{h}_{1}, \cdots$, $\bar{h}_{n}$, respectively.

Theorem 23. An element of $G \circ H$ may be written uniquely in any one of the three normal forms

$$
\begin{equation*}
\sum_{i=1}^{m} \sum_{j=1}^{n} a_{i j}\left(\bar{g}_{i} \cdot \bar{h}_{j}\right)=\sum_{i=1}^{m} \bar{g}_{i} \cdot h_{i}^{\prime}=\sum_{i=1}^{n} g_{j}^{\prime} \cdot \bar{h}_{j} . \tag{10.2}
\end{equation*}
$$

For, if

$$
\begin{equation*}
g_{k}=\sum b_{k i} \bar{g}_{i}, \quad h_{k}=\sum c_{k i} \bar{h}_{i} \tag{10.3}
\end{equation*}
$$

then the distributive laws give

$$
\begin{aligned}
& \sum_{k} g_{k} \cdot h_{k}=\sum_{k}\left(\sum_{i} b_{k i} \bar{g}_{i}\right) \cdot\left(\sum_{i} c_{k j} \bar{h}_{j}\right)=\sum_{k} \sum_{i}\left(\bar{g}_{i} \cdot \sum_{j} b_{k i} c_{k j} \bar{h}_{j}\right) \\
&=\sum_{i} \bar{g}_{i} \cdot \sum_{j} \sum_{k} b_{k i} c_{k j} \bar{h}_{j}, \text { etc. }
\end{aligned}
$$

thus (10.2) holds with

$$
\begin{equation*}
a_{i j}=\sum_{k} b_{k i} c_{k i}, \quad h_{i}^{\prime}=\sum_{j} a_{i j} \bar{h}_{j}, \quad g_{i}^{\prime}=\sum_{j} a_{j i} \bar{g}_{j} . \tag{10.4}
\end{equation*}
$$

Given any expression $\sum g_{i} \cdot h_{i}$ for $\alpha$ in $G \circ H$, the above procedure gives the normal forms in a unique manner; we must show that if $\sum g_{i} \cdot h_{i}=\sum g_{i}^{*} \cdot h_{i}^{*}$, the two expressions give the same result. It is sufficient to prove this for $\left(g+g^{*}\right) \cdot h$ and $g \cdot h+g^{*} \cdot h$, for $g \cdot\left(h+h^{*}\right)$ and $g \cdot h+g \cdot h^{*}$, and for $a g \cdot h$ and $g \cdot a h$. In each case, the proof is simple.

Let $C h_{H}(G)$ denote the group of linear maps (= continuous homomorphisms) of $G$ into $H$; this is a linear space of dimension $m n$. In particular, $L(G)=$ $C h_{R l}(G)$ is the group of linear real-valued functions in $G$, and is called the conjugate space of $G$. Here, isomorphism will mean continuous isomorphism $=$ operator isomorphism. The following theorem is well known.

Theorem 24. $L(G) \approx G$. Further, there is a natural isomorphism

$$
\begin{equation*}
L(L(G)) \approx G \tag{10.5}
\end{equation*}
$$

defined as follows. For any $g$ in $G, \phi(g)$ is the element of $L(L(G))$ which, for any $u$ in $L(G)$, has the value $u(g)$.

Let $\bar{u}_{i}(g)$ be the element of $L(G)$ such that $\bar{u}_{i}\left(\bar{g}_{i}\right)=1, \bar{u}_{i}\left(\bar{g}_{j}\right)=0(j \neq i)$. Clearly $\bar{u}_{1}, \cdots, \bar{u}_{m}$ form a base in $L(G)$; hence $L(G) \approx G$. Next, $\phi$ is linear. It is (1-1); for if $\phi(g)=0$, then $u(g)=0$ (all $u$ in $L(G)$ ), which implies $g=0$. Given any $v$ in $L(L(G))$, set $a_{i}=v\left(\bar{u}_{i}\right)$; then for any $u=\sum b_{i} \bar{u}_{i}$,

$$
u\left(\sum a_{i} \bar{g}_{i}\right)=\sum_{i} a_{i} \sum_{j} b_{j} \bar{u}_{j}\left(\bar{g}_{i}\right)=\sum a_{i} b_{i}=\sum b_{i} v\left(\bar{u}_{i}\right)=v(u)
$$

so that $\phi\left(\sum a_{1} \bar{g}_{i}\right)=v . \quad$ Clearly $\phi(a g)=a \phi(g) ;$ hence $\phi$ is an isomorphism.

Theorem 25. ${ }^{16}$ There is a natural isomorphism

$$
\begin{equation*}
C h_{H}(G) \approx L(G) \circ H \tag{10.6}
\end{equation*}
$$

given by

$$
\begin{equation*}
\phi\left(\sum u_{i} \cdot h_{i} ; g\right)=\sum u_{i}(g) h_{i} \tag{10.7}
\end{equation*}
$$

$\phi$ is clearly uniquely defined. If we write all elements of $L(G) \circ H$ in the third normal form $\sum u_{i} \cdot \bar{h}_{i}$, the properties of $\phi$ are easily established; for any element of $C h_{H}(G)$ can be written uniquely as $\sum u_{i}(g) \bar{h}_{i}$, and if this is the zero element, i.e., it is equal to zero in $H$ for all $g$, then all $u_{i}(g)=0$.

Corollary I. $G \circ H$ may be written in the form

$$
\begin{equation*}
G \circ H \approx L(L(G)) \circ H \approx C h_{H}(L(G)) \tag{10.8}
\end{equation*}
$$

The isomorphism of the first group into the last is given as follows. For $\sum g_{i} \cdot h_{i}$ in $G \circ H$ and $u$ in $L(G)$,

$$
\begin{equation*}
\phi\left(\sum g_{i} \cdot h_{i} ; u\right)=\sum u\left(g_{i}\right) h_{i} \tag{10.9}
\end{equation*}
$$

Corollary II. There is a natural isomorphism

$$
\begin{equation*}
C h_{G}(R l) \approx G \tag{10.10}
\end{equation*}
$$

for $u$ in $C h_{G}(R l), \phi(u)=u(1)$.
For $L(R l) \circ G \approx R l \circ G \approx G$. (Moreover, a direct proof is obvious.)
Theorem 26. $G \circ H$ is a linear space of dimension mn, with a base $\bar{g}_{1} \cdot \bar{h}_{1}, \ldots$, $\bar{g}_{m} \cdot \bar{h}_{n}$. If $\{U\}$ and $\{V\}$ are neighborhood systems in $G$ and $H$, respectively, defining their natural topologies, then either of the following neighborhood systems, if we use $p=\min (m, n)$,

$$
\begin{gather*}
N(U, V)=U \cdot V+\cdots+U \cdot V \quad \text { ( } p \text { summands }),  \tag{10.11}\\
N\left(U_{1}, U_{2}, \cdots ; V_{1}, V_{2}, \cdots\right)=\sum_{k} *\left(U_{k} \cdot V_{k}\right) \tag{10.12}
\end{gather*}
$$

defines the natural topology in $G \circ H^{17} \quad$ The multiplication $g \cdot h$ is continuous.
The first part of the theorem follows from Theorem 23. Let $N, N^{\prime}, N^{\prime \prime}$ denote natural neighborhoods and those of (10.11) and (10.12). Given an $N=N(\epsilon)$, consisting of all $\sum a_{i j} \bar{g}_{i} \cdot \bar{h}_{j}$ with $\sum a_{i j}^{2} \leqq \epsilon^{2}$, set $\epsilon_{1}=\epsilon /(m n)^{\frac{1}{2}}$, and let

$$
U_{k}=U\left(\epsilon_{1} / 2^{k}\right), \quad V_{k}=V(1), \quad(k=1,2, \cdots)
$$

be natural neighborhoods in $G$ and $H$. Then if $g_{k}=\sum b_{k i} \bar{g}_{i}$ is in $U_{k}$ and $h_{k}=$ $\sum c_{k j} \bar{h}_{j}$ is in $V_{k}$, (10.4) gives, if we use any finite number $\nu$ of summands in (10.12),

$$
\left|a_{i j}\right|=\left|\sum_{k} b_{k i} c_{k j}\right|<\sum_{k=1}^{\nu} \epsilon_{1} / 2^{k}<\epsilon_{1}=\epsilon /(m n)^{\frac{1}{2}}
$$

${ }^{16}$ This holds if at least one of $G, H$ is of finite dimension. Compare Theorem 22.
${ }^{17}$ If we map $R l$ into a curve everywhere dense on the torus, the topology of the torus gives an "unnatural" topology in $R l$. In $R l \circ R l$, either type of neighborhood as here given then contains the whole space.

Hence $\sum a_{i j}^{2}<\epsilon^{2}$, and $\sum_{k=1}^{\nu} g_{k} \cdot h_{k}$ is in $N$. Thus any $N$ contains an $N^{\prime \prime}$.
Next, given an $N^{\prime \prime}$, take

$$
U \subset U_{1} \cap \cdots \cap U_{p}, \quad V \subset V_{1} \cap \cdots \cap V_{p}
$$

Then clearly $N^{\prime}=N(U, V) \subset N^{\prime \prime}$.
Next, take any $N^{\prime}=N(U, V)$. Suppose for definiteness that $p=m$. Take $\epsilon_{1}$ so that $U\left(2 \epsilon_{1}\right) \subset U$ and $V\left(\epsilon_{1}\right) \subset V$, and set $\epsilon=\epsilon_{1}^{2}$. Now take any $\alpha$ of $G \circ H$ in $N(\epsilon)$; then we can write $\alpha=\sum a_{i j} \bar{g}_{i} \cdot \bar{h}_{j}$, with $\sum a_{i j}^{2}<\epsilon^{2}$. Also,

$$
\alpha=\sum_{i=1}^{m}\left(\epsilon_{1} \bar{g}_{i} \cdot \sum_{j=1}^{n} \theta a_{i j} \bar{h}_{j}\right), \quad \theta=\frac{1}{\epsilon_{1}} .
$$

As $m=p$ and $\epsilon_{1} \bar{g}_{i}$ is in $U\left(2 \epsilon_{1}\right) \subset U$, to show that $N(\epsilon) \subset N(U, V)$, it is sufficient to show that $\sum_{j} \theta a_{i j} \bar{h}_{i}$ is in $V\left(\epsilon_{1}\right)$. But

$$
\sum_{j} \theta^{2} a_{i j}^{2} \leqq \theta^{2} \sum_{i, j} a_{i j}^{2}<\theta^{2} \epsilon^{2}=\epsilon_{1}^{2}
$$

and this proves the statement.
The continuity of $g \cdot h$ is clear from the relation
$\sum\left(a_{i}+a_{i}^{\prime}\right) \bar{g}_{i} \cdot \sum\left(b_{j}+b_{j}^{\prime}\right) \bar{h}_{j}-\sum a_{i} \bar{g}_{i} \cdot \sum b_{j} \bar{h}_{j}=\sum\left(a_{i}^{\prime} b_{j}+a_{i} b_{j}^{\prime}+a_{i}^{\prime} b_{j}^{\prime}\right) \bar{g}_{i} \cdot \bar{h}_{j}$.
If $G$ and $H$ are metric, and hence scalar products $g \circ g^{\prime}$ and $h \circ h^{\prime}$ are defined, we may define scalar products and hence a metric in $G \circ H$ by

$$
\begin{equation*}
\left(\sum_{k} g_{k} \cdot h_{k}\right) \circ\left(\sum_{l} g_{l}^{\prime} \cdot h_{l}^{\prime}\right)=\sum_{k, l}\left(g_{k} \circ g_{l}^{\prime}\right)\left(h_{k} \circ h_{l}^{\prime}\right) .^{18} \tag{10.13}
\end{equation*}
$$

11. Tensor algebra. Let $G$ be a linear space of finite dimension $n$; in $\S 12$, it will be the "tangent space" at a point of a manifold. Any element of $G$ we shall call a contravariant vector. An element of $H=L(G)$ we call a covariant vector. Any element of the linear space

$$
\begin{equation*}
T(p, q)=G \circ \cdots \circ G \circ H \circ \cdots \circ H \quad(p \text { factors } G, q \text { factors } H) \tag{11.1}
\end{equation*}
$$

we shall call a tensor of contravariant order $p$ and covariant order $q$. As $L(p, q)$ is a linear space, we may add two tensors of the same type, and multiply a tensor by a real number. Using Theorems 3 and 4 in Part I, we have

$$
\begin{aligned}
&(G \circ \cdots \circ H \circ \cdots) \circ(G \circ \cdots \circ H \circ \cdots) \\
& \approx G \circ \cdots \circ G \circ \cdots \circ H \circ \cdots \circ H \circ \cdots .
\end{aligned}
$$

Hence a tensor of $T(p, q)$ and a tensor of $T\left(p^{\prime}, q^{\prime}\right)$ may be multiplied, giving a tensor of $T\left(p+p^{\prime}, q+q^{\prime}\right)$.

The process of contraction is as follows. To contract the element $g \cdot h$ of
${ }^{18}$ For a study of this metric in Hilbert spaces, see Murray and von Neumann, loc. cit.
$T(1,1)=G \circ H$, recall that $H=L(G)$, and set $\phi(g \cdot h)=h(g)$, a real number. To contract the element

$$
\alpha=\sum_{k} g_{k}^{1} \cdots g_{k}^{p} \cdot h_{k}^{1} \ldots h_{k}^{q} \quad \text { of } T(p, q)
$$

with respect to the $p$-th $g$ and the $q$-th $h$, for example, set

$$
\begin{equation*}
\phi(\alpha)=\sum_{k} h_{k}^{q}\left(g_{k}^{p}\right) g_{k}^{1} \cdots g_{k}^{p-1} \cdot h_{k}^{1} \cdots h_{k}^{q-1} \tag{11.2}
\end{equation*}
$$

this is an element of $T(p-1, q-1)$.
Let $\bar{g}_{1}, \cdots, \bar{g}_{n}$ form a base in $G$, and choose $\bar{h}^{i}$ so that $\bar{h}^{i}\left(\bar{g}_{j}\right)=\delta_{j}^{i}$; then $\bar{h}^{1}$, $\cdots, \bar{h}^{n}$ form a base in $H$. By the proof of Theorem 23, we may write any element of $T(p, q)$ uniquely in the normal form

$$
\begin{equation*}
\alpha=\sum_{i_{r}, i_{s}=1}^{n} A_{j_{1} \cdots j_{q}}^{i_{1} \cdots i_{p} \bar{g}_{i_{1}}} \cdots \bar{g}_{i_{p}} \bar{h}^{j_{1}} \ldots \bar{h}^{j_{q}} ; \tag{11.3}
\end{equation*}
$$

there are $n^{p+q}$ terms in the sum, and the $A_{j_{1} \cdots j_{q}}^{i_{1} \cdots i_{p}}$ are called the components of $\alpha$ in the coördinate system of the $\bar{g}_{i}$. Let us verify the laws of transformation of the components., Suppose we introduce the new base $g_{1}^{\prime}, \cdots, g_{n}^{\prime}$. Say

$$
\bar{g}_{i}=\sum_{k=1}^{n} a_{i}^{k} g_{k}^{\prime}, \quad g_{i}^{\prime}=\sum_{k=1}^{n} a_{i}^{\prime k} \bar{g}_{k}
$$

If $h^{\prime i}\left(g_{j}^{\prime}\right)=\delta_{j}^{i}$, then setting $h^{\prime i}=\sum b_{k}^{i} \hbar^{k}$ gives

$$
\delta_{j}^{i}=h^{\prime i}\left(g_{j}^{\prime}\right)=\sum_{k} b_{k}^{i} h^{k}\left(\sum_{l} a_{j}^{\prime \prime} \bar{g}_{l}\right)=\sum_{k, l} b_{k}^{i} a_{j}^{\prime l} \delta_{l}^{k}=\sum_{k} b_{k}^{i} a_{j}^{\prime k} .
$$

Hence $b_{j}^{i}=a_{i}^{i}$, and $\hbar^{i}=\sum a_{k}^{\prime i} h^{\prime k}$. Putting in (11.3) and using the distributive laws gives

$$
\alpha=\sum A_{j_{1} \cdots j_{q}}^{i_{1} \cdots i_{p}} a_{i_{1}}^{k_{1}} \cdots a_{i_{p}}^{k_{p}} a_{l_{1}}^{j_{1}} \cdots a_{l_{q}}^{j_{q}} g_{k_{1}}^{\prime} \cdots g_{k_{p}}^{\prime} \cdot h^{l_{1}} \cdots h^{\prime l_{q}} .
$$

Calling the new components $A_{l_{1} \cdots l_{q}}^{\prime k_{1} \cdots k_{p}}$, we have the ordinary laws of transformation. Note that

$$
h(g)=\sum_{i} B_{i} \hbar^{i}\left(\sum_{i} A^{j} \bar{g}_{j}\right)=\sum_{i, i} A^{j} B_{i} \bar{\hbar}^{i}\left(\bar{g}_{j}\right)=\sum_{i} A^{i} B_{i}
$$

so that the terms as here introduced agree with the usage in tensor algebra.
12. Tensor analysis. Let $M$ be a differentiable manifold. ${ }^{19}$ By a parametrized curve $C$ starting at the point $x_{0}$ in $M$ we shall mean a differentiable map $\phi$ of an interval $0 \leqq t \leqq \eta$ into $M$, with $\phi(0)=x_{0}$. Let us introduce a coördinate system into a neighborhood of $M$ about $x_{0}$, i.e., a (1-1) differentiable map $\theta$ of a region of the space $E$ of sets of $n$ numbers $\left(x^{1}, \cdots, x^{n}\right)$ into $M$, with non-vanishing Jacobian; say $\theta(0, \cdots, 0)=x_{0}$. Then $C$ translates into a curve $C^{\prime}$ in $E$,

[^7]given by $\theta^{-1}(\phi(t))$, if $\eta$ is small enough. We say two parametrized curves starting at $x_{0}$ are equivalent if, when translated into $E$, they have the same tangent vector (in both magnitude and direction). Clearly the definition of equivalence is independent of the coördinate system chosen. Hence the classes of equivalent curves form a set of elements intrinsically defined in $M$; we call these contravariant vectors at $x_{0}$. Using a fixed coördinate system, we may obtain a (1-1) correspondence between contravariant vectors $g$ at $x_{0}$ and vectors $v$ in $E$ at 0 , merely by choosing, as an interval, the line segment of $v$, parametrized so that $t=1$ at its end, and mapping it (or a portion of it, if it does not lie wholly in the region) into $M$ with $\theta$. We may add two contravariant vectors at $x$ by taking the corresponding vectors in $E$, adding, and mapping back into $M$. Again the result is independent of the coördinate system chosen; hence the contravariant vectors at $x_{0}$ form an intrinsically defined linear space, the tangent space $G\left(x_{0}\right)$ to $M$ at $x_{0}$.

We may obtain an intrinsic definition of $L\left(G\left(x_{0}\right)\right)=H\left(x_{0}\right)$ at $x_{0}$ by considering differentiable functions defined in a neighborhood of $x_{0}$, which vanish at $x_{0}$, and calling two functions equivalent if their partial derivatives at $x_{0}$ are the same in any coördinate system. To add covariant vectors, we need merely add the corresponding functions.

We shall consider briefly covariant differentiation in $M$. Suppose that to any two sufficiently near points $x_{0}$ and $x_{1}$ of $M$ corresponds a linear map $\Psi_{x_{1} x_{0}}$ of $G\left(x_{1}\right)$ into $G\left(x_{0}\right)$, so that certain simple continuity and linearity properties are satisfied, which we shall not make precise. This will define an affine connection ${ }^{20}$ in $M$. Now let $A(x)$ be a differentiable tensor field, being, for each $x$, an element of $T(p, q ; x)$ (using $G(x)$ ). Let $g$ be any contravariant vector at $x_{0}$, and let $C$, given by $\phi(t)$, be a corresponding parametrized curve. Then if $x_{t}=\phi(t)$, we may define

$$
\begin{equation*}
\nabla_{\sigma} A\left(x_{0}\right)=\lim _{t \rightarrow 0} \frac{1}{t}\left[\Psi_{x_{t} x_{0}} A\left(x_{t}\right)-A\left(x_{0}\right)\right] . \tag{12.1}
\end{equation*}
$$

(Of course $\Psi_{x_{t} x_{0}}$ may be used to translate a tensor at $x_{t}$ into a tensor at $x_{0}$.) For each $\dot{g}$ at $x_{0}, \nabla_{g} A\left(x_{0}\right)$ is a tensor of $T\left(p, q ; x_{0}\right)$, and it depends linearly on $g$; hence we have a linear map of $G\left(x_{0}\right)$ into $T\left(p, q ; x_{0}\right)$. By Theorem 25, there is a natural isomorphism

$$
C h_{T\left(p, q, x_{0}\right)}\left(G\left(x_{0}\right)\right) \approx T\left(p, q ; x_{0}\right) \circ L\left(G\left(x_{0}\right)\right) \approx T\left(p, q+1 ; x_{0}\right) .
$$

Hence, at each point $x_{0}$ we have a tensor of $T\left(p, q+1 ; x_{0}\right)$, of the same contravariant order as $A$ and of covariant order one greater; this is the covariant derivative of $A$ at $x_{0}$. Again, the definition is intrinsic.
${ }^{20}$ By using a coördinate system about $x_{0}$ and letting $x_{1} \rightarrow x_{0}$, we may use this connection to obtain an affine connection in the ordinary sense. Conversely, given an ordinary affine connection, we may define geodesics in $M$, and by following along them, define a connection as above. If we imbed $M$ in a Euclidean space as in Whitney, loc. cit., Theorem 1, we may realize the tangent spaces by tangent planes of dimension $n$, and define an affine connection by projecting one tangent plane onto another.
13. Products, general linear spaces. A representation $\sum g_{i} \cdot h_{i}$ of an element $\alpha$ of $G \circ H$ is minimal if there is no representation with fewer summands. The $\operatorname{rank} \rho(\alpha)$ of $\alpha$ is the number of summands in a minimal representation of $\alpha$. We consider $0=0.0$ as having no summands, and set $\rho(0)=0$.

We collect some known results (at least for finite dimensional spaces) in the following theorem.

Theorem 27. $G \circ H$ is a linear space. For any $\alpha$ in $G \circ H$ there are corresponding linear subspaces $G(\alpha)$ and $H(\alpha)$ of $G$ and $H$ with the following properties.
(a) There is a representation $\sum g_{i} \cdot h_{i}$ for $\alpha$ with $g_{i}$ in $G(\alpha), h_{i}$ in $H(\alpha)$. In any representation $\sum g_{i}^{\prime} \cdot h_{i}^{\prime}$ for $\alpha, G(\alpha) \subset G\left(g_{1}^{\prime}, \cdots\right), H(\alpha) \subset H\left(h_{1}^{\prime}, \cdots\right)$.
(b) $\operatorname{dim} G(\alpha)=\operatorname{dim} H(\alpha)=\rho(\alpha) ; G(\alpha)$ and $H(\alpha)$ are $G\left(g_{1}, \cdots\right)$ and $H\left(h_{1}\right.$, ...) in any minimal representation $\sum g_{i} \cdot h_{i}$ of $\alpha$.
(c) $\sum g_{i} \cdot h_{i}$ is minimal if and only if the sets $g_{1}, \ldots$ and $h_{1}, \ldots$ are each independent.
(d) If $g_{1}, \cdots, g_{m}$ and $h_{1}, \cdots, h_{n}$ are bases in subspaces $G^{\prime}$ of $G$ and $H^{\prime}$ of $H$, and $\alpha=\sum a_{i j} g_{i} \cdot h_{j}$, then $\rho(\alpha)=\operatorname{rank}\left\|a_{i j}\right\|$.
(e) If $g \cdot h=0$, then either $g=0$ or $h=0$.
(f) $g \cdot h=g^{\prime} \cdot h^{\prime} \neq 0$ if and only if $g^{\prime}=a g, h^{\prime}=(1 / a) g$ for some real $a$.

The first statement follows from Theorems 1 and 13.
Suppose $\alpha=\sum g_{i}^{\prime} \cdot h_{i}^{\prime}=\sum g_{i}^{\prime \prime} \cdot h_{i}^{\prime \prime}, g_{i}^{\prime}$ in $G^{\prime}, g_{i}^{\prime \prime}$ in $G^{\prime \prime}, h_{i}^{\prime}$ and $h_{i}^{\prime \prime}$ in $H^{*}$. Set $G^{*}=$ $G^{\prime} \cap G^{\prime \prime}$, and choose subspaces $G_{1}$ and $G_{2}$ (possibly containing 0 alone) such that

$$
G^{\prime}+G^{\prime \prime}=G^{*} \oplus G_{1} \oplus G_{2}, \quad G_{1} \subset G^{\prime}, \quad G_{2} \subset G^{\prime \prime}
$$

Choose bases $\left\{g_{i}^{*}\right\}$ in $G^{*},\left\{g_{i}^{1}\right\}$ in $G_{1},\left\{g_{i}^{2}\right\}$ in $G_{2}$; then all the $g$ 's form a base in $G^{\prime}+G^{\prime \prime}$. By Theorem 23, we may write uniquely, for some $h_{i}^{*}$, etc., in $H^{*}$,

$$
\alpha=\sum g_{i}^{*} \cdot h_{i}^{*}+\sum g_{i}^{1} \cdot h_{i}^{1}+\sum g_{i}^{2} \cdot h_{i}^{2}
$$

Now $G^{\prime}=G^{*} \oplus G_{1}$; hence, if we reduce $\sum g_{i}^{\prime} \cdot h_{i}^{\prime}$ to this normal form, the third group of terms will not appear. As the normal form is unique, the third sum $=0$. Similarly, as $G^{\prime \prime}=G^{*} \oplus G_{2}$, the second sum vanishes. Hence $\alpha=$ $\sum g_{i}^{*} \cdot h_{i}^{*}$ can be expressed by using $g^{\prime}$ s from $G^{\prime} \cap G^{\prime \prime}$ alone. Hence there is a minimal subspace $G(\alpha)$ which may be used. Find similarly a minimal $H(\alpha)$. Now $\alpha$ can be expressed, by using $G(\alpha)$ and $H^{\prime} \supset H(\alpha)$, and $G^{\prime} \supset G(\alpha)$ and $H(\alpha)$. Choosing bases properly in $G^{\prime}$ and $H^{\prime}$ and using the first normal form, we see at once that $\alpha$ may be expressed, using $G(\alpha)$ and $H(\alpha)$. This proves (a).

Next we show that rank $\left\|a_{i j}\right\|$ depends on $\alpha$ alone. Suppose $\left\{g_{i}\right\}$ and $\left\{g_{i}^{\prime}\right\}$ are bases in $G^{\prime},\left\{h_{i}\right\}$ is a base in $H^{\prime}$, and $\alpha=\sum a_{i j} g_{i} \cdot h_{j}=\sum a_{k j}^{\prime} g_{k}^{\prime} \cdot h_{j}$. If $g_{i}=$ $\sum_{k} b_{k i} g_{k}^{\prime}$, then $a_{k j}^{\prime}=\sum_{i} b_{k i} a_{i j}$, i.e., $A^{\prime}=B A$. As $B$ is non-singular, rank $A=$ rank $A^{\prime}$. Similarly, a change of base in $H^{\prime}$ causes no change in the rank. If $G^{\prime \prime} \supset G^{\prime}$ and $H^{\prime \prime} \supset H^{\prime}$, and we choose bases in these spaces containing the above $g_{i}$ and $h_{i}$, then $\sum a_{i j} g_{i} \cdot h_{j}$ is also a normal form for $\alpha$, using $G^{\prime \prime}$ and $H^{\prime \prime}$. The new $\left\|a_{i j}\right\|$ is the old $\left\|a_{i j}\right\|$ with extra rows and columns of zeros; the ranks are therefore the same. Now given any two representations of $\alpha$ in normal
form, using the pair $G^{\prime}, H^{\prime}$ and the pair $G^{\prime \prime}, H^{\prime \prime}$, we may also write $\alpha$ in normal form, using $G^{\prime}+G^{\prime \prime}$ and $H^{\prime}+H^{\prime \prime}$. The above proof shows that all ranks of matrices are the same.

If $\sum_{i=1}^{\rho(\alpha)} g_{i} \cdot h_{i}$ is minimal, then obviously the sets $\left\{g_{i}\right\}$ and $\left\{h_{i}\right\}$ are independent. They form bases in spaces $G^{\prime}$ and $H^{\prime}$, say, and the expression $\sum g_{i} \cdot h_{i}$ is then in normal form. The matrix is the unit matrix, and hence is of rank $\rho(\alpha)$. This proves (d). As $G(\alpha) \subset G^{\prime}$, and $\operatorname{dim} G(\alpha)<\rho(\alpha)$ is clearly impossible, $G(\alpha)=$ $G^{\prime}$ and $\operatorname{dim} G(\alpha)=\rho(\alpha)$; similarly for $H(\alpha)$. (b) is now proved. If $\alpha=$ $\sum_{i=1}^{r} g_{i} \cdot h_{i}$ and the sets $\left\{g_{i}\right\},\left\{h_{i}\right\}$ are independent, then we have a representation in normal form, with matrix of rank $r$; hence $r=\rho(\alpha)$, and $\sum g_{i} \cdot h_{i}$ is minimal. This proves (c).

To prove (e), suppose $g \neq 0, h \neq 0$. Then $g \cdot h$ is minimal, by (c), hence $\rho(g \cdot h)=1$, and $g \cdot h \neq 0$. (f) follows from the fact that for $\alpha=g \cdot h=g^{\prime} \cdot h^{\prime} \neq 0$, $G(\alpha)=$ all multiples of $g=$ all multiples of $g^{\prime}$.

Theorem 28. If $G^{\prime}$ is a linear subspace of $G$, then there is a natural isomorphism $G^{\prime} \circ H \approx \sum^{*}\left(G^{\prime} \cdot H\right)$.

Using $\sum g_{i} \times h_{i}$ in $G^{\prime} \circ H$, set $\phi\left(\sum g_{i} \times h_{i}\right)=\sum g_{i} \cdot h_{i} . \quad$ Clearly $\phi$ is a uniquely defined homomorphism onto the whole of $\sum^{*}\left(G^{\prime} \cdot H\right)$. Suppose $\phi\left(\sum g_{i} \times h_{\mathfrak{i}}\right)=$ $\sum g_{i} \cdot h_{i}, \sum g_{i} \times h_{i} \neq 0$. We may suppose $\sum g_{i} \times h_{i}$ is minimal. Then the sets $\left\{g_{i}\right\}$ and $\left\{h_{i}\right\}$ are independent, and hence $\sum g_{i} \cdot h_{i}$ is minimal, by the last theorem, and $\sum g_{i} \cdot h_{i} \neq 0$. Hence $\phi$ is (1-1), and this completes the proof.
14. On topological linear spaces. We shall use the following definition. If $G^{\prime} \subset G^{*}$, a projection of $G^{*}$ into $G^{\prime}$ is a linear map of $G^{*}$ into $G^{\prime}$ such that every element of $G^{\prime}$ is fixed.

Definition. We shall call a topological linear space $G$ a linear space with sets $U, V, \cdots$, called neighborhoods (of 0 ), such that:
(1) 0 is in every $U$;
(2) given $U, V$, there is a $W \subset U \cap V$;
(3) given $U$, there is a $V$ such that for $-1 \leqq a \leqq 1, a V \subset U$;
(4) given $U$, there is a $V$ with $V+V \subset U$;
(5) for every $U$ and every $g$ in $G$ there is an $a$ with $g$ in $a U$;
(6) for every finite dimensional subspace $G^{\prime}$ of $G$ and every natural neighborhood $U^{\prime}$ in the space $G^{\prime}$ (see $\S 10$ ), there is a neighborhood $U$ in $G$ with the following property. If $G^{*} \supset G^{\prime}$ is a finite dimensional subspace, then there is a projection of $G^{*}$ into $G^{\prime}$ which carries $U \cap G^{*}$ into $U^{\prime}$.

We shall relate this definition to Definition 2b of von Neumann. ${ }^{21}$
Note that (6) implies a separation postulate: If $g \neq 0$, then there is a $U$ which does not contain $g$. The reason for using our (6) is that with it one may prove the same property, and hence the separation postulate, in tensor products.

[^8]Theorem 29. A topological linear space (even with (6) replaced by a separation postulate) is a regular Hausdor.ff space; $g+g^{\prime}$ and ag are each continuous in both variables.

As our definition has all the properties in N, Definition 2b, except his (2) and (7), and a separation postulate holds, his proof holds without change. ${ }^{22}$ We may now use $U_{c l}=$ closure of $U$ and $U_{i}=$ inner points of $U$, etc., as in N .

Preparatory to proving Theorem 30, we note the following facts.
(a) If a set of sets $U$ satisfies the above properties, then so do the sets $U_{c l}$, the sets $U_{i}$, and the sets $U-U\left(=\right.$ all $g-g^{\prime}, g$ and $g^{\prime}$ in $\left.U\right)$.
(b) The sets $U_{c l},\left(U_{c l}\right)_{i}$, and $U-U$ define the same topology (i.e., give the same definition of $S_{i}$ for any $S$ ) as the sets $U$.

These hold also if N, Definition 2 b is used. To prove these facts, first note that N, Theorem 3, in particular, $(a S)_{c l}=a S_{c l}$, holds for closures; the proof is essentially the same. (a) and (b) now follow easily, using especially: $U_{c l} \subset U+U ; V+V \subset U$ implies $V \subset U_{i}$.
(c) In a convex space as in N , we may suppose that the $U$ are convex, and either closed or open, and that $-U=U$.

For we may use either the $U_{c l}$ or the $\left(U_{c l}\right)_{i}$. The $U_{c l}$ are convex, by N , Theorem 13. To prove this for $\left(U_{c l}\right)_{i}=S_{i}$, take $g$ and $g^{\prime}$ in $S_{i}$ and $0<a<1$. Set $g^{*}=a g+(1-a) g^{\prime}$, and choose $V$ so that $g+V \subset S, g^{\prime}+V \subset S$. Then

$$
g^{*}+V \subset a(g+V)+(1-a)\left(g^{\prime}+V\right) \subset S_{c l}=S
$$

and hence $g^{*}$ is in $S_{i}$. Finally, replace each $U$ by $U-U=U^{\prime}$; then all former properties hold, and $-U^{\prime}=U^{\prime}$.

Lemma 6. Let $G$ be a convex topological linear space as in N , satisfying our (c). Let $g_{1}, \ldots, g_{\mu}, g^{\prime}$, be independent; let $g_{1}, \cdots, g_{\mu}$ determine the subspace $G_{1}$ of $G$, and the whole set, the subspace $G^{*}$. Let $m$ be an integer $\leqq \mu$. Let $U$ be a neighborhood such that

$$
\begin{equation*}
\text { if } \sum_{i=1}^{\mu} a_{i} g_{i} \text { is in } U, \quad \text { then } \quad\left|a_{i}\right| \leqq t_{i} \quad(i=1, \ldots, m) \tag{14.1}
\end{equation*}
$$

Then there is a projection of $G^{*}$ into $G_{1}$ such that the projection of $U \cap G^{*}$ satisfies the same inequalities.

It will not restrict the generality if we suppose that $t_{i}$ are the smallest numbers such that (14.1) holds. As $-U=U$, no inequality in (14.1) can be bettered now.

First, suppose we have two elements

$$
\begin{equation*}
g_{1}^{\prime \prime}=\sum a_{i} g_{i}+c g^{\prime}, \quad g_{2}^{\prime \prime}=\sum b_{i} g_{i}+c g^{\prime}, \quad \text { in } U \tag{14.2}
\end{equation*}
$$

then as $U=-U$ is convex,

$$
\frac{1}{2}\left(g_{1}^{\prime \prime}-g_{2}^{\prime \prime}\right)=\sum \frac{1}{2}\left(a_{i}-b_{i}\right) g_{i} \quad \text { is in } U
$$

${ }^{22}$ In Hausdorff, Mengenlehre, Berlin, 1927, there is an error on p. 229: (5) does not follow from (6), as shown by a space in which the only open sets are the null set and the whole space. In $N$, proof of Theorem 6, one should mention that a separation postulate holds, as a consequence of Definition 2b, (2).
and hence

$$
\begin{equation*}
\left|a_{i}-b_{i}\right| \leqq 2 t_{i} \quad(i=1, \cdots, m) \tag{14.3}
\end{equation*}
$$

Now take any $c \geqq 0$ for which there is an element of the form (14.2) in $U$; let $\phi_{i}(c)$ and $\psi_{i}(c)(i=1, \cdots, m)$ be the greatest lower bound and least upper bound respectively of all numbers $d$ such that for some numbers $a_{1}, \ldots$, $a_{i-1}, a_{i+1}, \cdots, a_{\mu}$,

$$
\sum_{i \neq i} a_{i} g_{j}+\left( \pm t_{i}+d\right) g_{i}+c g^{\prime} \quad \text { is in } U \quad(- \text { for } \phi,+ \text { for } \psi)
$$

In other words, $\phi_{i}(c)$ and $\psi_{i}(c)$ show how much $U$ sticks out beyond the rectangle of the $t_{i}$, in the $g_{i}$ direction, at the height $c$, with respect to the direction of $g^{\prime}$. By the choice of the $t_{i}, \phi_{i}(0)=\psi_{i}(0)=0$.

By (14.3), $\phi_{i}(c) \geqq \psi_{i}(c)$. We now show that
(14.4) if $0<c<c^{\prime}$, then $\frac{\phi_{i}(c)}{c} \leqq \frac{\phi_{i}\left(c^{\prime}\right)}{c^{\prime}}, \quad \frac{\psi_{i}(c)}{c} \geqq \frac{\psi_{i}\left(c^{\prime}\right)}{c^{\prime}}$.

Suppose, for instance, the first inequality is false. Then there are numbers $a_{i}(j \neq i), e$, such that

$$
\begin{array}{cc}
g_{1}^{\prime}=\sum_{i \nless i} a_{i} g_{j}+\left(-t_{i}+d\right) g_{i}+c^{\prime} g^{\prime} & \text { is in } U, \\
d=\frac{c^{\prime}}{c}\left[\phi_{i}(c)-e\right], & e>0 .
\end{array}
$$

By the choice of the $t_{i}$, there is an element

$$
g_{2}^{\prime}=\sum_{j \neq i} b_{i} g_{j}+\left(-t_{i}+d^{\prime}\right) g_{i} \text { in } U, \quad d^{\prime}<\frac{c^{\prime} e}{c^{\prime}-c}
$$

As $U$ is convex,

$$
\frac{c}{c^{\prime}} g_{1}^{\prime}+\frac{c^{\prime}-c}{c^{\prime}} g_{2}^{\prime}=\sum_{j \neq i} a_{j}^{\prime} g_{j}+\left(-t_{i}+\frac{c}{c^{\prime}} d+\frac{c^{\prime}-c}{c^{\prime}} d^{\prime}\right) g_{i}+c g^{\prime}
$$

is in $U$. But also

$$
\frac{c}{c^{\prime}} d+\frac{c^{\prime}-c}{c^{\prime}} d^{\prime}=\phi_{i}(c)-e+\frac{c^{\prime}-c}{c^{\prime}} d^{\prime}<\phi_{i}(c)
$$

contradicting the definition of $\phi_{i}(c)$.
The inequalities show that we may define

$$
\begin{equation*}
\phi_{i}^{\prime}=\lim _{c \rightarrow 0+} \frac{\phi_{i}(c)}{c}, \quad \psi_{i}^{\prime}=\lim _{c \rightarrow 0+} \frac{\psi_{i}(c)}{c} \tag{14.5}
\end{equation*}
$$

then

$$
\begin{equation*}
\frac{\phi_{i}(c)}{c} \geqq \phi_{i}^{\prime} \geqq \psi_{i}^{\prime} \geqq \frac{\psi_{i}(c)}{c} \quad(c>0 ; i=1, \ldots, m) \tag{14.6}
\end{equation*}
$$

Set

$$
\begin{equation*}
g^{\prime \prime}=g^{\prime}+\sum_{i=1}^{m} \phi_{i}^{\prime} g_{i} \tag{14.7}
\end{equation*}
$$

we shall show that if we project $U$ along the direction of $g^{\prime \prime}$ into $G_{1}$, i.e., use $\phi\left(\sum a_{i} g_{i}+a^{\prime \prime} g^{\prime \prime}\right)=\sum a_{i} g_{i}$, then (14.1) will hold for the projection. As $-U=U$, it will be sufficient to consider the part of $U$ with $c>0$. If this is false, say for $i$, then there is an element

$$
\begin{equation*}
\sum_{j=1}^{\mu} a_{j} g_{j}+c g^{\prime \prime} \text { in } U, \quad c>0, \quad a_{i}>t_{i} \quad \text { or } \quad a_{i}<-t_{i} \tag{14.8}
\end{equation*}
$$

Using (14.7), we have

$$
\begin{equation*}
\sum_{j \neq i}^{j \leq m}\left(a_{i}+c \phi_{j}^{\prime}\right) g_{j}+\sum_{j=m+1}^{\mu} a_{i} g_{j}+\left(a_{i}+c \phi_{i}^{\prime}\right) g_{i}+c g^{\prime} \text { in } U \tag{14.9}
\end{equation*}
$$

Suppose first that $a_{i}<-t_{i}$. Then

$$
a_{i}+c \phi_{i}^{\prime}<-t_{i}+c \frac{\phi_{i}(c)}{c}=-t_{i}+\phi_{i}(c)
$$

contradicting the definition of $\phi_{i}(c)$. Next, if $a_{i}>t_{i}$, then

$$
a_{i}+c \phi_{i}^{\prime}>t_{i}+c \psi_{i}^{\prime} \geqq t_{i}+\psi_{i}(c)
$$

contradicting the definition of $\psi_{i}(c)$. This completes the proof.
Theorem 30. Any convex topological linear space as in N is a topological linear space as here defined, even if his (2) is replaced by a separation postulate.

We may suppose his neighborhoods satisfy our (c). We must prove our (6). Let $g_{1}, \cdots, g_{m}$ form a base for $G^{\prime}$, and choose $t_{1}, \cdots, t_{m}$ so that all points $\sum a_{i} g_{i},\left|a_{i}\right| \leqq t_{i}$, lie in $U^{\prime}$. Let $R$ be the closed region $\left|a_{i}\right| \leqq t_{i}$, and let $A$ be its boundary. For each $g$ in $A$, we may choose a $U(g)$ not containing it, and a $V(g)$ so that $V(g)-V(g) \subset U(g)$. As the operations in $G$ are continuous, $\sum a_{k} g_{k}$ is continuous in the $a_{k}$, so the $(V(g))_{i} \cap G^{\prime}\left(S_{i}=\right.$ inner points of $\left.S\right)$ are open in the natural topology in $G^{\prime}$; hence a finite number of the sets $g+V(g) \cap$ $G^{\prime}$ cover $A$. Let $U$ be a neighborhood in the corresponding set $V\left(g_{1}\right) \cap \ldots$ $\cap V\left(g_{\lambda}\right)$. Now $U$ contains no element of $A$. For suppose $g$ is in $A \cap U$. Say $g$ is in $g_{k}+V\left(g_{k}\right)$. Then as $g$ is in $U \subset V\left(g_{k}\right), g_{k}$ is in $V\left(g_{k}\right)-V\left(g_{k}\right) \subset U\left(g_{k}\right)$, a contradiction. As $U$ is convex, $U \cap G^{\prime}$ is in the complement of $A$ in $R$.

Let $g_{m+1}^{\prime}, \cdots, g_{n}^{\prime}$ form, with $g_{1}, \ldots, g_{m}$, a base in $G^{*}$ (if $G^{*} \neq G^{\prime}$ ), and let $G_{i}$ be the space generated by $g_{1}, \cdots, g_{i}^{\prime}(i=m+1, \cdots, n)$. We shall prove, by induction on $i$, that $G_{i}$ can be projected into $G^{\prime}$ so that $U \cap G_{i}$ goes into $R$; as $R \subset U^{\prime}$, the case $i=n$ gives the theorem. There will be elements $g_{m+1}, \cdots$, $g_{n}$ such that $g_{1}, \ldots, g_{i}$ also determine $G_{i}$, and the projection of $G_{i}$ into $G^{\prime}$ is with respect to $g_{m+1}, \cdots, g_{i}$ :

$$
\phi\left(\sum_{k=1}^{i} a_{k} g_{k}\right)=\sum_{k=1}^{m} a_{k} g_{k}
$$

Suppose we have found the elements $g_{m+1}, \cdots, g_{\mu}$. As the projection of $G_{\mu}$ into $G^{\prime}$ carries $U \cap G_{\mu}$ into $R$, (14.1) is satisfied. Hence we may apply Lemma 6 with $g^{\prime}=g_{\mu+1}^{\prime}, G^{*}=G_{\mu+1}$; this gives a projection of $G_{\mu+1}$ into $G_{\mu}$ such that the projection of $U \cap G_{\mu+1}$ satisfies (14.1). Let $g_{\mu+1}$ give the direction of the projection; then projecting $G_{\mu+1}$ into $G^{\prime}$ with respect to $g_{m+1}, \cdots, g_{\mu+1}$ carries $U \cap$ $G_{\mu+1}$ into $R$, as required.
15. Products, topological linear spaces. We prove

Theorem 31. If $G$ and $H$ are topological linear spaces, so is $G \circ H$, the topology being given by (10.12). (We may use either open or closed neighborhoods in $G$ and in $H$; see §14.) The multiplication $g \cdot h$ is continuous. The topology in $G \circ H$ depends only on the topologies in $G$ and in $H$, not on the neighborhood systems employed.

First, $G \circ H$ is a linear space, by Theorem 27 . We shall prove the postulates of $\S 14$. (1) is trivial. To prove (2), take any two neighborhoods $N\left(U_{1}, \cdots\right.$; $\left.V_{1}, \cdots\right)=N\left(U_{i} ; V_{i}\right)$, and $N\left(U_{i}^{\prime} ; V_{i}^{\prime}\right)$. Choose $U_{i}^{\prime \prime}$ in $U_{i} \cap U_{i}^{\prime}$ and $V_{i}^{\prime \prime}$ in $V_{i} \cap V_{i}^{\prime}$; then

$$
N\left(U_{i}^{\prime \prime} ; V_{i}^{\prime \prime}\right) \subset N\left(U_{i} ; V_{i}\right) \cap N\left(U_{i}^{\prime} ; V_{i}^{\prime}\right)
$$

To prove (3), given $N\left(U_{i} ; V_{i}\right)$, choose $U_{i}^{\prime}$ so that $a U_{i}^{\prime} \subset U_{i}$ if $|a| \leqq 1(i=$ $1,2, \cdots)$. Then

$$
a N\left(U_{i}^{\prime} ; V_{i}^{\prime}\right)=N\left(a U_{i}^{\prime} ; V_{i}^{\prime}\right) \subset N\left(U_{i} ; V_{i}\right)
$$

To prove (4), take any $N\left(U_{i} ; V_{i}\right)$. Choose $U_{i}^{\prime}$ and $V_{i}^{\prime}$ so that

$$
U_{i}^{\prime} \subset U_{2 i-1} \cap U_{2 i}, \quad V_{i}^{\prime} \subset V_{2 i-1} \cap V_{2 i}
$$

Now take any $\sum g_{i} \cdot h_{i}$ and $\sum g_{i}^{\prime} \cdot h_{i}^{\prime}$ in $N\left(U_{i}^{\prime} ; V_{i}^{\prime}\right)$. As $g_{1} \cdot h_{1}$ is in $U_{1}^{\prime} \cdot V_{1}^{\prime} \subset U_{1} \cdot V_{1}$, $g_{1}^{\prime} \cdot h_{1}^{\prime}$ is in $U_{1}^{\prime} \cdot V_{1}^{\prime} \subset U_{2} \cdot V_{2}, g_{2} \cdot h_{2}$ is in $U_{2}^{\prime} \cdot V_{2}^{\prime} \subset U_{3} \cdot V_{3}$, etc., we see that $\sum g_{i} \cdot h_{i}+$ $\sum g_{i}^{\prime} \cdot h_{i}^{\prime}$ is in $N\left(U_{i} ; V_{i}\right)$.

To prove (5), take any $\sum_{i=1}^{s} g_{i} \cdot h_{i}$ and any $N\left(U_{i} ; V_{i}\right)$. Choose $U_{i}^{*}$ and $V_{i}^{*}$ so that

$$
c U_{i}^{*} \subset U_{i}, \quad c V_{i}^{*} \subset V_{i}, \quad(|c| \leqq 1 ; i=1, \cdots, s)
$$

take $a_{i}$ and $b_{i}$ so that

$$
g_{i} \text { is in } a_{i} U_{i}^{*}, \quad h_{i} \text { is in } b_{i} V_{i}^{*}
$$

and let $a$ be the largest of the $\left|a_{i}\right|$ and $\left|b_{i}\right|$. Then

$$
a_{i} U_{i}^{*}=a\left(a_{i} / a\right) U_{i}^{*} \subset a U_{i}, \quad \text { etc. } ;
$$

it follows that $\sum g_{i} \cdot h_{i}$ is in

$$
a^{2} N\left(U_{i} ; V_{i}\right)=N\left(a U_{i} ; a V_{i}\right)
$$

We now prove (6). Let $F^{\prime}$ be a subspace of $F=G \circ H$, generated by $f_{1}, \cdots$, $f_{s}$. Set (see Theorem 27)

$$
G^{\prime}=G\left(f_{1}\right)+\cdots+G\left(f_{s}\right), \quad H^{\prime}=H\left(f_{1}\right)+\cdots+H\left(f_{s}\right) .
$$

Let $g_{1}, \ldots, g_{m}$ and $h_{1}, \ldots, h_{n}$ be bases in $G^{\prime}$ and $H^{\prime}$; set $f_{i j}=g_{i} \cdot h_{i}$. Then the $f_{i j}$ form a base (see Theorem 26) in a space $F^{\prime \prime} \supset F^{\prime}$. Take a fixed projection of $F^{\prime \prime}$ into $F^{\prime \prime}$. Given a natural neighborhood $N^{\prime}$ in $F^{\prime}$, we may choose a natural neighborhood $N^{\prime \prime}$ in $F^{\prime \prime}$ which projects into a subset of $N^{\prime}$. As any projection of an $F^{*}$ into $F^{\prime \prime}$ combines with the above projection to give a projection of $F^{*}$ into $F^{\prime}$, it is sufficient to prove (6) with $F^{\prime}, N^{\prime}$ replaced by $F^{\prime \prime}, N^{\prime \prime}$.

Choose $\epsilon>0$ so that any $\sum a_{i j} f_{i j}$ with each $\left|a_{i j}\right| \leqq \epsilon$ is in $N^{\prime \prime}$. Let $A$ and $B$ be the sets of elements $\sum a_{i} g_{i}$ and $\sum b_{i} h_{i}$ in $G^{\prime}$ and $H^{\prime}$ with $\left|a_{i}\right| \leqq \frac{1}{2} \epsilon,\left|b_{i}\right| \leqq 1$. Choose $U_{1}$ in $G$ by (6) so that any $U_{1} \cap G^{*}$ can be projected into $A$, and choose $V_{1}$ in $H$ so that any $V_{1} \cap H^{*}$ can be projected into $B$. Choose $U_{2}, U_{3}, \cdots$ so $2 U_{i} \subset U_{i-1}$, and set $V_{2}=V_{3}=\cdots=V_{1} . \quad$ Set $N=N\left(U_{i} ; V_{i}\right)$.

Now take any $F^{*} \supset F^{\prime \prime}$. Choose a base $f_{1}^{*}, \cdots, f_{t}^{*}$ in $F^{*}$, and set $G^{*}=\sum G\left(f_{i}^{*}\right)$, $H^{*}=\sum H\left(f_{i}^{*}\right)$. Choose projections of $G^{*}$ into $G^{\prime}$ and $H^{*}$ into $H^{\prime}$ so $U_{1} \cap G^{*}$ goes into $A$ and $V_{1} \cap H^{*}$ goes into $B$. If $G_{1}$ is the subset of $G^{*}$ projecting into 0 in $G^{\prime}$, and $g_{m+1}, \cdots, g_{\mu}$ is a base in $G_{1}$, then $g_{1}, \cdots, g_{\mu}$ is a base in $G^{*}$; choose a base $h_{1}, \cdots, h_{y}$ in $H^{*}$ similarly. Now any element of $F^{*}$ can be written uniquely in the form

$$
f=\sum_{(i, j)=(1,1)}^{(m, n)} a_{i j} f_{i j}+\sum^{\prime} a_{i j} g_{i} \cdot h_{i}
$$

where in $\sum^{\prime}$, either $i>m$ or $j>n$. (Not all such elements need be in $F^{*}$.) Dropping out the second group of terms defines a projection of $F^{*}$ into $F^{\prime \prime}$.

We shall show by induction that any ( $U_{i} \cdot V_{i}$ ) $\cap F^{*}$ projects into elements $\sum a_{k l} f_{k l}$ with $\left|a_{k l}\right| \leqq \epsilon / 2^{i}$; it will follow that $N=\sum_{i}^{*}\left(U_{i} \cdot V_{i}\right)$ projects into $N^{\prime \prime}$.

Take first any $\alpha$ in $\left(U_{1} \cdot V_{1}\right) \cap F^{*}$; we may suppose $\alpha \neq 0$. Then $\alpha=g \cdot h$, $g$ in $U_{1}, h$ in $V_{1}$. As $\alpha$ is in $F^{*}, G(\alpha) \subset G^{*}$. But also $G(\alpha) \subset G(g)$; hence $G(\alpha) \subset G^{*} \cap G(g)$. As $\alpha \neq 0, G(\alpha)$ contains elements $\neq 0$, which implies that $g$ is in $G^{*}$. Similarly $h$ is in $H^{*}$. Say

$$
g=\sum_{i=1}^{\mu} a_{i} g_{i}, \quad h=\sum_{j=1}^{\nu} b_{i} h_{j} .
$$

Then as $g$ projects into $A$ and $h$ into $B, g \cdot h$ projects into

$$
\sum_{(i, j)=(1,1)}^{(m, n)} a_{i} b_{j} f_{i j}, \quad\left|a_{i} b_{j}\right|<\frac{1}{2} \epsilon
$$

so that the statement holds for $\left(U_{1} \cdot V_{1}\right) \cap F^{*}$. Supposing it holds for $k-1$, we shall prove it for $k$. Take any $g$ in $U_{k}$ and $h$ in $V_{k}$ such that $g \cdot h$ is in $F^{*}$. Then

$$
2 g \text { is in } 2 U_{k} \subset U_{k-1}, \quad h \text { is in } V_{k-1}
$$

so that $2(g \cdot h)$ is in $\left(U_{k-1} \cdot V_{k-1}\right) \cap F^{*}$, and hence projects into $\sum a_{i j} f_{i j}$ with $\left|a_{i j}\right| \leqq$ $\epsilon / 2^{k-1}$. Hence the required inequality on $g \cdot h$ bolds. This completes the proof of (6).

To show that $g \cdot h$ is continuous, as + is continuous in $G \circ H$ (Theorem 29), and

$$
\begin{equation*}
\left(g+g^{\prime}\right) \cdot\left(h+h^{\prime}\right)-g \cdot h=g \cdot h^{\prime}+g^{\prime} \cdot h+g^{\prime} \cdot h^{\prime} \tag{15.1}
\end{equation*}
$$

it is sufficient to show that $g \cdot h^{\prime}$ is continuous in $h^{\prime}$ at $h^{\prime}=0, g^{\prime} \cdot h$ is continuous in $g^{\prime}$ at $g^{\prime}=0$, and $g^{\prime} \cdot h^{\prime}$ is continuous in $g^{\prime}$ and $h^{\prime}$ at $g^{\prime}=0, h^{\prime}=0$. For the first case, given $N=N\left(U_{i} ; V_{i}\right)$, choose $a$ so that $g$ is in $a U_{1}$, and choose $V$ so that $a V \subset V_{1}(\mathrm{~N}$, Theorem 1 , with $n=1)$. Then

$$
g \cdot V \subset a U_{1} \cdot V=U_{1} \cdot a V \subset U_{1} \cdot V_{1} \subset N
$$

The second case is similar. The third is clear, as $U_{1} \cdot V_{1} \subset N$.
Finally, let $\{U\},\{\bar{U}\}$ and $\{V\},\{\bar{V}\}$ be equivalent neighborhood systems in $G$ and $H$, respectively. Given an $N\left(U_{i} ; V_{i}\right)$, choose $\bar{U}_{i} \subset U_{i}$ and $\bar{V}_{i} \subset V_{i}$ $(i=1,2, \cdots)$; then $\bar{N}\left(\bar{U}_{i} ; \bar{V}_{i}\right) \subset N\left(U_{i} ; V_{i}\right) . \quad$ Similarly find an $N$ in any $\bar{N}$. Hence the $\{N\}$ and $\{\bar{N}\}$ are equivalent. The theorem is now completely proved.

## III. Topological groups

16. The topological tensor product. An Abelian topological group $G$ is an Abelian group which is at the same time a Hausdorff space, ${ }^{23}$ and in which $\phi\left(g, g^{\prime}\right)=g+g^{\prime}$ and $\psi(g)=-g$ are continuous. If $U, U^{\prime}, \cdots$ are the neighborhoods of 0 , we may let the sets $g+U, g+U^{\prime}, \cdots$ be the neighborhoods of the element $g$, without altering the topology. If we assume that the separation postulate in Hausdorff, page 229, (4), holds, then the postulate (5) follows.

We shall say the space $G$ is sequence-separable if it contains a finite or denumerable set of points forming a dense set. ${ }^{24}$

If $G$ and $H$ are sequence-separable topological groups, we define their topological tensor product $G \circ H$, or tensor product simply, as follows. Let $\bar{g}_{1}, \bar{g}_{2}, \ldots$ and $\bar{h}_{1}, \bar{h}_{2}, \cdots$ be sequences of points dense in $G$ and $H$, respectively. Let $P_{1}, P_{2}, \ldots$ be a sequence of pairs of elements, $P_{i}=\left(\bar{g}_{\mu_{i}}, \bar{h}_{\nu_{i}}\right)$, such that each pair ( $\bar{g}_{j}, \bar{h}_{k}$ ) occurs infinitely often among the $P_{i}$. Let $T^{\prime \prime}$ be the discrete tensor product of $G$ and $H$, with elements $\sum g_{i} \times h_{i}$. For each sequence $U_{1}$, $U_{2}, \ldots$ of neighborhoods (of 0 ) in $G$ and each sequence $V_{1}, V_{2}, \ldots$ in $H$, set

$$
\begin{align*}
& Q_{i}^{\prime}(U, V)=\bar{g}_{\mu_{i}} \times V+U \times \bar{h}_{\nu_{i}}+U \times V \\
& N^{\prime}\left(U_{1}, \cdots ; V_{1}, \cdots\right)=\sum_{i}^{*} Q_{i}^{\prime}\left(U_{i}, V_{i}\right) \tag{16.1}
\end{align*}
$$

Next, call two elements $\alpha, \beta$ of $T^{\prime}$ equivalent, $\alpha \sim \beta$, if every $\alpha+N$ contains $\beta$ or vice versa, or if there is a succession $\alpha=\alpha_{0}, \alpha_{1}, \cdots, \alpha_{n}=\beta$, with $\alpha_{i}$ and

[^9]$\alpha_{i+1}$ equivalent as above. The sets of equivalent elements form the elements of the tensor product $T=G \circ H$. The neighborhoods $N$ of 0 in $G \circ H$ are the images of the sets $N^{\prime}$ in $T^{\prime}$; they are obtained by replacing $\times$ by $\cdot$ in (16.1). Addition in $T$ is the image of addition in $T^{\prime}$. The element $\sum g_{i} \cdot h_{i}$ in $T$ is the image of $\sum g_{i} \times h_{i}$ in $T^{\prime}$.

Theorem 32. $G \circ H$ is a sequence-separable Abelian topological group; the multiplication $g \cdot h$ satisfies (1.1), and is continuous. The topology in $G \circ H$ is independent of the sequences $\left\{\bar{g}_{i}\right\},\left\{\bar{h}_{i}\right\}$, and of the neighborhood systems $\{U\}$, $\{V\}$, employed.

We begin by showing that $T^{\prime \prime}$ has all the properties of a topological group, except for the separation postulate. First we prove Hausdorff's postulates (B), (C) (loc. cit., p. 228). Given $N^{\prime}\left(U_{1}, \cdots ; V_{1}, \cdots\right)=N^{\prime}\left(U_{l} ; V_{l}\right)$ and $N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right)$, take $U_{i}^{\prime \prime} \subset U_{i} \cap U_{i}^{\prime}$ and $V_{i}^{\prime \prime} \subset V_{i} \cap V_{i}^{\prime}(i=1,2, \cdots)$; then clearly

$$
\begin{equation*}
N^{\prime}\left(U_{l}^{\prime \prime} ; V_{l}^{\prime \prime}\right) \subset N^{\prime}\left(U_{l} ; V_{l}\right) \cap N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \tag{16.2}
\end{equation*}
$$

To prove (C), it is sufficient to show that, for any $N^{\prime}\left(U_{l} ; V_{l}\right)$ and any $\alpha$ in $N^{\prime}\left(U_{l} ; V_{l}\right)$, there is an $N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right)$ with

$$
\begin{equation*}
\alpha+N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \subset N^{\prime}\left(U_{l} ; V_{l}\right) \tag{16.3}
\end{equation*}
$$

As $\alpha$ is in $N^{\prime}\left(U_{l} ; V_{l}\right)$, it is in $\sum_{i=1}^{s} Q_{i}^{\prime}\left(U_{i} ; V_{i}\right)$ for some $s$. Choose numbers $\phi(1)>s, \phi(2)>\phi(1), \phi(3)>\phi(2), \cdots$ so that $P_{i}=P_{\phi(i)}$, and set $U_{i}^{\prime}=U_{\phi(i)}$, $V_{i}^{\prime}=V_{\phi(i)}$. Then

$$
\begin{aligned}
Q_{i}^{\prime}\left(U_{i}^{\prime}, V_{i}^{\prime}\right) & =\bar{g}_{\mu_{i}} \times V_{i}^{\prime}+U_{i}^{\prime} \times \bar{h}_{r_{i}}+U_{i}^{\prime} \times V_{i}^{\prime} \\
= & \bar{g}_{\mu_{\phi(i)}} \times V_{\phi(i)}+U_{\phi(i)} \times \bar{h}_{\nu_{\phi}(i)}+U_{\phi(i)} \times V_{\phi(i)}=Q_{\phi(i)}^{\prime}\left(U_{\phi(i)}, V_{\phi(i)}\right)
\end{aligned}
$$

hence $\sum_{i}^{*} Q_{i}^{\prime}\left(U_{i}^{\prime}, V_{i}^{\prime}\right) \subset \sum_{i>s}^{*} Q_{i}^{\prime}\left(U_{i}, V_{i}\right)$, and (16.3) follows.
We show that the group operations in $T^{\prime}$ are continuous. Given $N^{\prime}\left(U_{l} ; V_{l}\right)$, take

$$
U_{i}^{\prime} \subset U_{i} \cap\left(-U_{i}\right), \quad V_{i}^{\prime} \subset-V_{i}
$$

then

$$
-Q_{i}^{\prime}\left(U_{i}^{\prime}, V_{i}^{\prime}\right)=\bar{g}_{\mu_{i}} \times\left(-V_{i}^{\prime}\right)+\left(-U_{i}^{\prime}\right) \times \bar{h}_{\nu_{i}}+U_{i}^{\prime} \times\left(-V_{i}^{\prime}\right) \subset Q_{i}^{\prime}\left(U_{i}, V_{i}\right) ;
$$

hence

$$
\begin{equation*}
N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \subset-N^{\prime}\left(U_{l} ; V_{l}\right) \tag{16.4}
\end{equation*}
$$

and $-\alpha$ is continuous in $\alpha$. To show that $\alpha+\beta$ is continuous, we must find $N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right)$ corresponding to $N^{\prime}\left(U_{l} ; V_{l}\right)$ such that

$$
\begin{equation*}
N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right)+N^{\prime}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \subset N^{\prime}\left(U_{l} ; V_{l}\right) \tag{16.5}
\end{equation*}
$$

Choose in succession integers

$$
\phi(1), \quad \psi(1)>\phi(1), \quad \phi(2)>\psi(1), \quad \psi(2)>\phi(2), \quad \cdots
$$

so that $P_{i}=P_{\phi(i)}=P_{\psi(i)}$. Take

$$
U_{i}^{\prime} \subset U_{\phi(i)} \cap U_{\psi(i)}, \quad V_{i}^{\prime} \subset V_{\phi(i)} \cap V_{\psi(i)}
$$

Then as $g_{\mu_{\phi(i)}}=g_{\mu_{i}}$, etc.,

$$
Q_{i}^{\prime}\left(U_{i}^{\prime}, V_{i}^{\prime}\right) \subset Q_{\phi(i)}^{\prime}\left(U_{\phi(i)}, V_{\phi(i)}\right) \cap Q_{\psi(i)}^{\prime}\left(U_{\psi(i)}, V_{\psi(i)}\right)
$$

Hence

$$
Q_{i}^{\prime}(\cdots)+Q_{i}^{\prime}(\cdots) \subset Q_{\phi(i)}^{\prime}(\cdots)+Q_{\psi(i)}^{\prime}(\cdots)
$$

and (16.5) follows.
We now consider equivalent elements in $T^{\prime}$. First we prove
${ }^{(*)}$ If $\alpha \sim \beta$, then for every $N^{\prime}, \alpha+N^{\prime}$ contains $\beta$.
For suppose there is a succession $\alpha=\alpha_{0}, \alpha_{1}, \cdots, \alpha_{n}=\beta$, such that for each $i$, either every $\alpha_{i}+N^{\prime}$ contains $\alpha_{i+1}$, or every $\alpha_{i+1}+N^{\prime}$ contains $\alpha_{i}$. The latter condition implies the former. For given an $N^{\prime}$, choose $N_{1}^{\prime} \subset-N^{\prime}$ by (16.4); then as $\alpha_{i}$ is in $\alpha_{i+1}+N_{1}^{\prime}, \alpha_{i+1}$ is in $\alpha_{i}-N_{1}^{\prime} \subset \alpha_{i}+N^{\prime}$. Next, given an $N^{\prime}$, choose $N_{1}^{\prime}$ (using (16.5)) so that

$$
N_{1}^{\prime}+N_{1}^{\prime}+\cdots+N_{1}^{\prime} \subset N^{\prime} \quad(n \text { summands })
$$

Setting $A_{k}=N_{1}^{\prime}+\cdots+N_{1}^{\prime}(k$ summands), we have

$$
\alpha+N^{\prime} \supset \alpha_{0}+A_{n} \supset \alpha_{1}+A_{n-1} \supset \ldots \supset \alpha_{n-1}+N_{1}^{\prime} \supset \beta
$$

as required.
Next we prove that $T$ is a topological group. Let $\theta(\alpha)$ be the element of $T$ containing the element $\alpha$ of $T^{\prime}$. We must show that addition in $T$ is uniquely defined; this is so if $\alpha \sim \alpha^{\prime}$ and $\beta \sim \beta^{\prime}$ imply $\alpha+\beta \sim \alpha^{\prime}+\beta^{\prime}$. Given any $N^{\prime}$, choose $N_{1}^{\prime}$ so that $N_{1}^{\prime}+N_{1}^{\prime} \subset N^{\prime}$. By the property ( ${ }^{*}$ ), $\alpha+N_{1}^{\prime} \supset \alpha^{\prime}$ and $\beta+N_{1}^{\prime} \supset \beta^{\prime}$; hence

$$
(\alpha+\beta)+N^{\prime} \supset\left(\alpha+N_{1}^{\prime}\right)+\left(\beta+N_{1}^{\prime}\right) \supset \alpha^{\prime}+\beta^{\prime}
$$

and $\alpha+\beta \sim \alpha^{\prime}+\beta^{\prime}$. Further,

$$
\theta(\alpha+\beta)=\theta(\alpha)+\theta(\beta)
$$

so that $\theta$ is a homomorphism of $T^{\prime}$ into $T$ (which is clearly an Abelian group). To prove that $T$ is a Hausdorff space, suppose $N_{1}=\theta\left(N_{1}^{\prime}\right)$ and $N_{2}=\theta\left(N_{2}^{\prime}\right)$ are given; take $N^{\prime} \subset N_{1}^{\prime} \cap N_{2}^{\prime}$; then $N=\theta\left(N^{\prime}\right) \subset N_{1} \cap N_{2}$. Next, suppose $\alpha^{*}$ is in $N=\theta\left(N^{\prime}\right)$; then $\alpha^{*}=\theta(\alpha), \alpha$ in $N^{\prime} . \quad$ Choose $N_{1}^{\prime}$ so that $\alpha+N_{1}^{\prime} \subset N^{\prime}$; then $\alpha^{*}+\theta\left(N_{1}^{\prime}\right)=\theta\left(\alpha+N_{1}^{\prime}\right) \subset N$. To prove the separation postulate, suppose $\alpha^{*} \neq 0$. Say $\alpha^{*}=\theta(\alpha)$. As $\theta(0)=0, \alpha$ is not $\sim 0$, and there is an $N^{\prime}$ not containing $\alpha$. Set $N=\theta\left(N^{\prime}\right)$; then $\alpha^{*}$ is not in $N$. For if it were, then we would have $\alpha^{*}=\theta(\beta), \beta$ in $N^{\prime}$ and $\beta \sim \alpha$; but taking $N_{1}^{\prime}$ by (16.3) so that $\beta+N_{1}^{\prime} \subset N^{\prime}$, the property $\left({ }^{*}\right)$ gives $\alpha \subset \beta+N_{1}^{\prime} \subset N^{\prime}$, a contradiction. To prove that the operations in $T$ are continuous, given $N=\theta\left(N^{\prime}\right)$, take $N_{1}^{\prime} \subset-N^{\prime}$; then $N_{1}=\theta\left(N_{1}^{\prime}\right) \subset-N$; also given $N=\theta\left(N^{\prime}\right)$, choose $N_{1}^{\prime}$ so that $N_{1}^{\prime}+N_{1}^{\prime} \subset N^{\prime}$; then $\theta\left(N_{1}^{\prime}\right)+\theta\left(N_{1}^{\prime}\right) \subset N$.

Next, (1) holds, as it holds for $\times$. We shall now show that $g \cdot h$ is continuous. First we show that it is continuous in $h$ at $h=0$; given $N=N\left(U_{l} ; V_{l}\right)$, we must find $V$ so that $g \cdot V \subset N$. As the $\bar{g}_{i}$ are dense in $G$, we may choose $j$ so that $g-\bar{g}_{\mu_{j}}$ is in $U_{1} . \quad$ Choose $V \subset V_{1} \cap V_{j}$; then

$$
g \cdot V \subset\left(g-\bar{g}_{\mu_{j}}\right) \cdot V+\bar{g}_{\mu_{i}} \cdot V \subset U_{1} \cdot V_{1}+\bar{g}_{\mu_{j}} \cdot V_{1} \subset N .
$$

Similarly $g \cdot h$ is continuous in $g$ at $g=0$. Further, $g \cdot h$ is continuous in both variables at $g=0, h=0$; for $U_{1} \cdot V_{1} \subset N\left(U_{l} ; V_{l}\right)$. Finally, as addition is continuous in $T$, (15.1) shows that $g \cdot h$ is continuous.

Next we show that $T$ is sequence-separable; in fact, that the set of all finite sums $\sum \bar{g}_{p_{i}} \cdot \bar{h}_{q_{i}}$ is dense in $T$. As each element of $T$ is a finite sum $\sum g_{i} \cdot h_{i}$ and + is continuous, it is sufficient to show that for any $g \cdot h$ and any $N=N\left(U_{l} ; V_{l}\right)$ there is a $\bar{g}_{i} \cdot \bar{h}_{j}$ in $g \cdot h+N$. As $\cdot$ is continuous, we may choose $U$ and $V$ so that $(g+U) \cdot(h+V) \subset g \cdot h+N$; we need now merely take $\bar{g}_{i}$ in $g+U$ and $\bar{h}_{j}$ in $h+V$.

That the topology in $T$ is independent of the neighborhood systems chosen is trivial; see the end of the proof of Theorem 31. We must still show that the topology is independent of the choice of the $\bar{g}_{i}$ and $\bar{h}_{i}$. By symmetry, it is sufficient to show that if $\left\{\bar{g}_{i}\right\}$ is replaced by the dense sequence $\left\{g_{i}^{*}\right\}$, then any $N\left(U_{l} ; V_{l}\right)$ contains an $N^{*}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right)$, defined in terms of the $g_{i}^{*}$. Let $\xi_{i}, \eta_{i}$ replace $\mu_{i}, \nu_{i}$. Given $N\left(U_{l} ; V_{l}\right)=N_{0}$, choose $N_{1}, N_{2}, \cdots$ in succession so that $N_{i+1}+N_{i+1} \subset N_{i} . \quad$ As $\cdot$ and + are continuous, we can choose $U_{i}^{\prime}$ and $V_{i}^{\prime}$ so that

$$
Q_{i}^{*}=\bar{g}_{\xi_{i}} \cdot V_{i}^{\prime}+U_{i}^{\prime} \cdot \bar{h}_{\eta_{i}}+U_{i}^{\prime} \cdot V_{i}^{\prime} \subset N_{i} ;
$$

then for any $s$,

$$
\begin{aligned}
\sum_{i=1}^{s} Q_{i}^{*} & \subset N_{1}+\cdots+N_{s-1}+N_{s} \subset N_{1}+\cdots+N_{s-2}+N_{s-1}+N_{s-1} \\
& \subset N_{1}+\cdots+N_{s-2}+N_{s-2} \subset \cdots \subset N_{1}+N_{1} \subset N_{0}
\end{aligned}
$$

and hence $N^{*}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \subset N_{0}$, as required. This completes the proof of the theorem.
Theorem 33. Let $g_{1}^{*}, g_{2}^{*}, \ldots$ and $h_{1}^{*}, h_{2}^{*}, \cdots$ be (finite or infinite) sequences such that the sets $\sum a_{i} q_{i}^{*}$ and $\sum a_{i} h_{i}^{*}$ (integral $a_{i}$ ) are dense in $G$ and $H$, respectively. Then we may use these sequences in place of dense sequences in defining the topology in $G \circ H$.

Let $h_{1}, h_{2}, \ldots$ be either the above sequence $h_{1}^{*}, h_{2}^{*}, \ldots$, or a dense sequence in $H$. Arrange all $\sum a_{i} g_{i}^{*}$ in a sequence $\bar{g}_{1}, \bar{g}_{2}, \ldots$. Let $N\left(U_{l} ; V_{l}\right)$ be defined in terms of the sets $\left\{\bar{g}_{i}\right\},\left\{h_{i}\right\}$, and $N^{*}\left(U_{l} ; V_{l}\right)$, in terms of the sets $\left\{g_{i}^{*}\right\},\left\{h_{i}\right\}$. It is sufficient to show that these two sets of neighborhoods give the same topology in $T$. As the $g_{i}^{*}$ occur among the $\bar{g}_{i}$, it is clear that any $N$ contains an $N^{*}$; we must prove the converse.

Let $P_{i}=\left(\bar{g}_{\mu_{i}}, h_{\nu_{i}}\right)$ and $P_{i}^{*}=\left(g_{\xi_{i}}^{*}, h_{\eta_{i}}\right)$ define the sequences of pairs defining
the $N$ and the $N^{*}$. If $\bar{g}_{\mu_{i}}=\sum_{j} a_{i j} g_{i}^{*}$, set $m(i)=\sum_{j}\left|a_{i j}\right|$. Then $\bar{g}_{\mu_{i}} \cdot V$ is contained in $m(i)$ terms of the form $g_{j}^{*} \cdot( \pm V)$, and $Q_{i}\left(U_{i}^{\prime}, V_{i}^{\prime}\right)$ is contained in $m(i)+2$ terms of forms appearing (except for the $\pm$ ) in $N^{*}\left(U_{l} ; V_{l}\right)$. For each $i$ we may choose $m(i)+2$ numbers $\phi_{1}(i), \cdots, \phi_{m(i)+2}(i)$ such that $\phi_{k}(i) \neq \phi_{l}(j)$ whenever $i \neq j$, and the $k$-th part into which $Q_{i}$ is split corresponds to part of $Q_{\phi_{k}(i)}^{*}$. Then if the $U_{i}^{\prime}$ and $V_{i}^{\prime}$ are chosen small enough, we will have

$$
Q_{i}\left(U_{i}^{\prime}, V_{i}^{\prime}\right) \subset \sum_{k=1}^{m(i)} Q_{\phi_{k}(i)}^{*}\left(U_{\phi_{k}(i)}, V_{\phi_{k}(i)}\right)
$$

and hence $N\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \subset N^{*}\left(U_{l} ; V_{l}\right)$, as required.
17. Relation to linear spaces; examples. We shall show that whenever the definitions of tensor products in Parts II and III both apply, they coincide.

Theorem 34. If $G$ and $H$ are sequence-separable topological linear spaces, then their topological tensor product $T$ is the same as their topological reduced tensor product $T^{*}$.

Let $\sum g_{i} \times h_{i}$ and $\sum g_{i} \cdot h_{i}$ denote elements of $T^{*}$ and $T$, respectively. Set $\phi\left(\sum g_{i} \times h_{i}\right)=\sum g_{i} \cdot h_{i}$; we shall show that $\phi$ is a topological isomorphism. To show that $\phi$ is uniquely defined, we must show that $a g \cdot h=g \cdot a h$ for any real $a$; but this follows from the continuity of $g \cdot h$ (see $\S 10$ ). $\phi$ is a homomorphism; we shall show that it is continuous. Use $N\left(U_{l} ; V_{l}\right)$ in $T$ and $N^{*}\left(U_{l} ; V_{l}\right)$ in $T^{*}$. Given $N\left(U_{l} ; V_{l}\right)$, we wish to find $N^{*}\left(U_{l}^{\prime} ; V_{l}^{\prime}\right)$ mapping into it. From (10.12) and (16.1) it is apparent that we may use $U_{i}^{\prime}=U_{i}, V_{i}^{\prime}=V_{i}$.

Next we show that for any $N^{*}=N^{*}\left(U_{l} ; V_{l}\right)$, there is an $N=N\left(U_{l}^{\prime} ; V_{l}^{\prime}\right) \subset$ $\phi\left(N^{*}\right)$. Say $\bar{g}_{1}, \bar{g}_{2}, \ldots$ and $\bar{h}_{1}, \bar{h}_{2}, \ldots$ are the dense sequences used in $G$ and $H$, and $P_{1}, P_{2}, \cdots, P_{i}=\left(\bar{g}_{\mu_{i}}, \bar{h}_{\nu_{i}}\right)$, the pairs. By $\S 14$, (5), we may choose for each $i$ a number $a_{i}$ such that $\bar{g}_{\mu_{i}}$ is in $a_{i} U_{3 i-2}$, and a number $b_{i}$ such that $h_{\nu_{i}}$ is in $b_{i} V_{3 i-1}$. By von Neumann, loc. cit., Theorem 1 (with $n=1$ ), there is a $V_{i}^{\prime \prime}$ such that $a_{i} V_{i}^{\prime \prime} \subset V_{3 i-2}$, and a $U_{i}^{\prime \prime}$ such that $b_{i} U_{i}^{\prime \prime} \subset U_{3 i-1}$. Choose

$$
U_{i}^{\prime} \subset U_{i}^{\prime \prime} \cap U_{3 i}, \quad V_{i}^{\prime} \subset V_{i}^{\prime \prime} \cap V_{3 i}
$$

Now

$$
\begin{aligned}
\bar{g}_{\mu_{i}} \cdot V_{i}^{\prime}+U_{i}^{\prime} \cdot \bar{h}_{\nu_{i}}+U_{i}^{\prime} \cdot V_{i}^{\prime} & \subset a_{i} U_{3 i-2} \cdot \frac{1}{a_{i}} V_{3 i-2}+\frac{1}{b_{i}} U_{3 i-1} \cdot b_{i} V_{3 i-1}+U_{3 i} \cdot V_{3 i} \\
& =\phi\left(U_{3 i-2} \times V_{3 i-2}+U_{3 i-1} \times V_{3 i-1}+U_{3 i} \times V_{3 i}\right)
\end{aligned}
$$

hence $N \subset \phi\left(N^{*}\right)$.
Clearly $\phi$ maps $T^{*}$ into the whole of $T$. When we have shown that $\phi$ is (1-1), the proof will be completed. Let $T^{\prime}$ be the discrete tensor product of $G$ and $H$; use $g \circ h$ here. Take any $\alpha^{*}=\sum g_{i} \times h_{i} \neq 0$ in $T^{*}$; then $\alpha^{\prime}=\sum g_{i} \circ h_{i}$ is a corresponding element of $T^{\prime}$. There is an $N^{*}=N^{*}\left(U_{l} ; V_{l}\right)$ which does not contain $\alpha^{*}$. Construct $U_{1}^{\prime}, U_{2}^{\prime}, \ldots$ and $V_{1}^{\prime}, V_{2}^{\prime}, \cdots$ by the method given above, and set

$$
N^{\prime}=\sum_{i}^{*}\left(\bar{g}_{\mu_{i}} \circ V_{i}^{\prime}+U_{i}^{\prime} \circ \bar{h}_{\nu_{i}}+U_{i}^{\prime} \circ V_{i}^{\prime}\right)
$$

The $\operatorname{map} \psi\left(\sum g_{i}^{\prime} \circ h_{i}^{\prime}\right)=\sum g_{i}^{\prime} \times h_{i}^{\prime}$ of $T^{\prime}$ into $T^{*}$ is uniquely defined. By the choice of the $U_{i}^{\prime}$ and $V_{i}^{\prime}, \psi\left(N^{\prime}\right) \subset N^{*}$; hence $\alpha^{\prime}$ is not in $N^{\prime}$. Therefore, by the property $\left({ }^{*}\right)$ in $\S 16, \alpha^{\prime}$ is not $\sim 0$, so that the corresponding element $\sum g_{i} \cdot h_{i}$ of $T$ is $\neq 0$. Consequently $\alpha^{*} \neq 0$ implies $\phi\left(\alpha^{*}\right) \neq 0$, and $\phi$ is (1-1).
Examples. That the topology in (10.12) cannot be used in the general case is shown by the example $I_{0} \circ R l$. A neighborhood $U$ of 0 in $I_{0}$ is 0 itself; hence $U \cdot V=0 \cdot V=0$, and $I_{0} \circ R l$ would be discrete; the multiplication $a \cdot g$ would not be continuous. However, the sets $1 . V$ form a neighborhood system in $I_{0} \circ R l$. In fact, if $G$ has a finite number of generators $\bar{g}_{1}, \cdots, \bar{g}_{n}$, then the sets

$$
\begin{equation*}
\bar{g}_{1} \cdot V_{1}+\cdots+\bar{g}_{n} \cdot V_{n} \quad\left(V_{1}, \cdots, V_{n} \text { neighborhoods in } H\right) \tag{17.1}
\end{equation*}
$$

form a neighborhood system in $G \circ H$. This is an easy consequence of Theorem 33 (compare Theorem 26).

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[^0]:    Received February 23, 1938; presented to the American Mathematical Society, February 26, 1938. See Proceedings of the National Academy of Sciences, vol. 23(1937), p. 290.
    ${ }^{1}$ This is so even if $G$ and $H$ are not Abelian; see Theorem 11. If $G$ and $H$ are linear or topological, we use a slightly different definition.
    ${ }^{2}$ J. L. Dorroh, Concerning the direct product of algebras, Annals of Mathematics, vol. 36 (1935), pp. 882-885. The author is indebted to the referee for pointing out this paper to him.
    ${ }^{3}$ In linear spaces, the group of real numbers also is a unit.
    ${ }^{4}$ Some of these results have been derived independently by H. E. Robbins.

[^1]:    ${ }^{5}$ This definition was suggested to me by H. E. Robbins.

[^2]:    ${ }^{7}$ See F. J. Murray and J. von Neumann, On rings of operators, Annals of Mathematics, vol. 37(1936), pp. 116-229, Chapter I. As a bounded operator $A$ in $G$ corresponds uniquely to an element $f$ in $G: A(g)=(f, g)$, their space $G \otimes G$ corresponds to our $G \circ G$. M. H. Stone and J. W. Calkin have also considered a direct definition of $G \circ G$ such as we give. Compare also M. Kerner, Abstract differential geometry, Compositio Mathematica, vol. 4 (1937), pp. 308-341.
    ${ }^{8}$ See Alexandroff-Hopf, Topologie I, pp. 585-586 and p. 233, (15), and H. Freudenthal, Fundamenta Mathematicae, vol. 29(1937). The definition of $G \circ H$ is indirect. The case that one of $G, H$ is a free group has been studied by H. Freudenthal, Compositio Mathematica, vol. 4(1937), pp. 145-234, Chapter III.

[^3]:    ${ }^{9} g_{\mu}$ is the element of $G_{\mu}$ corresponding to $g$ in $G$.

[^4]:    ${ }^{10}$ Compare J. L. Dorroh, loc. cit.

[^5]:    ${ }^{12}$ See R. Baer, The subgroup of elements of finite order of an Abelian group, Annals of Mathematics, vol. 37(1936), pp. 766-781, (1; 1).

[^6]:    ${ }^{15}$ The group is necessarily Abelian. Compare §3, (e). If $G$ is not linear, it can be made so by taking $R l \circ G$; see Theorem 12, §6.

[^7]:    ${ }^{19}$ See, for instance, O. Veblen-J. H. C. Whitehead, Foundations of Differential Geometry, Cambridge Tracts in Mathematics, No. 29, 1933, or H. Whitney, Differentiable manifolds, Annals of Mathematics, vol. 37(1936), pp. 645-680.

[^8]:    ${ }^{21}$ J. von Neumann, On complete topological spaces, Transactions of the American Mathematical Society, vol. 37(1935), pp. 1-20. We refer to this paper as N.

[^9]:    ${ }^{23}$ See Hausdorff, loc. cit. Note that neighborhoods are open sets here.
    ${ }^{24}$ For metric spaces, this is the same as separability.

